

Magnetostrictive Position Sensors

G-Series Linear Position Sensor Analog and Digital Pulse Outputs

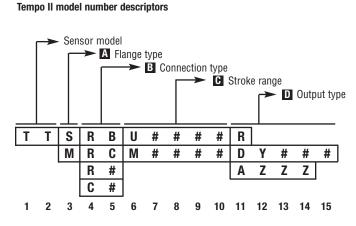
# **Cross Reference**



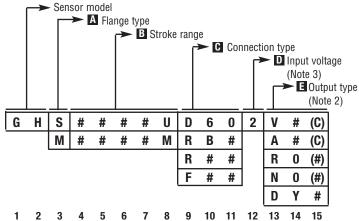
550967 A



#### Replacement and retrofit options for the Tempo II sensor



## G-Series model number descriptors (Tempo II retrofit options)



Notes:

- 1. Many of the G-Series "backwards compatible" options shown on page 2 are not included in other G-Series literature.
- The characters (C) and (#) in parenthesis, as shown above, indicate model number characters that are not usually needed, and are used only for certain options.
- G-Series input voltage option 2 is used for backwards compatibility for +15 Vdc power supplies.

Contact MTS Applications Engineering for any Tempo II options that are not cross referenced in this document.



All specifications are subject to change. Please contact MTS for specifications that are critical to your needs. Go to www.temposonics.com for the latest list of G-Series support documentation.

G-S	Series Cross Reference																												
A F	lange	е Тур	e (and	l pressi	ire ho	using)																							
Temp	o II r	node	l num	ıber exa	mple:					_					G-Sei	ries e	quiva	alent	mode	el nun	nber	exam	ple:						
Τ	T	S													G	H	S									2			
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1	2	3	4	5	67	8	9	10	11	12	13	14	15		1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
Temp RB	0 11	<u>You</u> 1. S e T 2. S T 3. S	r Tem elect xtens able / elect able f elect	it option option ' ion cab A on pag option ' 3 on pag option ' tegral c	<u>as an i</u> 'D60" le con ge 3. 'D60" ge 3. 'RB#"	for intended of the for intended of the for intended of the formation of the formation of the for intended of the for intended of the for intended of the formation of the forma	egral with egral	6-pir the fi 6-pir	n DIN ield-in n DIN	male stalle male	conne d in-li conne	ector, ne 6 <sup>.</sup> ector,	, AND -pin DI , AND	repl IN f use	lace y emale the a	our c con dapt	comp necto er cal	lete e or, pa ble pa	extens rt no. art no	sion c 3704 . 253	23, s 243-	solder x or 2	ring re 25324	equire 4-x, (	éd, (so (sold :	old se separ	epara ately	tely). ). See	е
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а	b	C	d			а	b				II an	d the	GHm	odel.	The	other	cha	racte	ers (b	-d) to	or le	emp	0	indi	cate	e th	e nur	nbe	roto		culati	ons.	For	the G	H
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<u>Analog</u>	<u>Output Rar</u>	ige (Note 2)	Notes:	
AS1Z (Note 3) AS2Z	V0 V2	0 to +10 Vdc -10 to +10 Vdc	<ol> <li>When replacing Tempo II sensors with more than 15 circulations, consult MTS Applications Engineering.</li> </ol>	
AS3Z AS4Z AS5Z AS6Z	V7 V1 V3 V6	0 to -10 Vdc +10 to 0 Vdc. +10 to -10 Vdc -10 to 0 Vdc.	<ol> <li>Format shown is: [value at Null (Setpoint 1)] to [value at Span (Setpoint 2)].</li> <li>The G-Series does not utilize Tempo II type "performance mode" options. Therefore, the characteristic shown as "Z" is not needed for the GH models.</li> </ol>	oter
ACOZ	V_C		ut. Consult MTS Application Engineering. Usually signifies custom analog setpoints.	

Та		

Table A
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Existing extension cable wire of	color code	Installing 6-pin DIN female	connector, part no. 370423	
If cable has striped colors	If cable has solid colors	Pin-out for Analog output	Pin-out for Digital-Pulse output	Pin-out for Neuter output only
White/Blue Stripe	White	6	6	6
Blue/White Stripe	Brown	No Connection	No Connection	No Connection
White/Orange Stripe	Gray	2	1	1
Orange/White Stripe	Pink	1	2	No Connection
White/Green Stripe	Red	5	5	5
Green/White Stripe	Blue	No Connection	No Connection	No Connection
White/Brown Stripe	Black	3	No Connection	No Connection (note 1)
Brown/White Stripe	Violet	4	No Connection	2
White/Gray Stripe	Yellow	No Connection	3	3
Gray/White Stripe	Green	No Connection	4	4

Note 1: If the White/Brown Stripe (or Black) wire was used as DC ground for the Tempo II or L-Series sensor being replaced then the DC ground connection at the controller must be changed to use the White/Blue Stripe (or White) wire.

Table B

Female straight exit D6 to male RB connection adapter cables							
1 ft. cable length, standard, for G-Series analog output sensors	Part no. 253243-1						
1 ft. cable length, standard, for G-Series digital-pulse and neuter output sensors	Part no. 253243-2						
5 ft. cable length, for G-Series analog output sensors	Part no. 253244-1						
5 ft. cable length, for G-Series digital-pulse and neuter output sensors	Part no. 253244-2						

## **Tables continued**

#### Table C

If your system has an Analog Output Module (AOM)	If your system has a Digital Interface Box (DIB)
You can connect the GH model sensor directly to your controller/interface card (bypassing the AOM) if: 1. The AOM output is displacement only (voltage or current).	You can connect the GH model sensor directly to your controller/interface card (bypassing the DIB) if:
<ol> <li>There is no velocity output from the AOM.</li> <li>There are no dual channel outputs from the AOM.</li> </ol>	The DIB is configured to use 15 or less recirculations.
4. There are no external null or scale adjustment potentiometer inputs to the AOM.	Contact MTS Applications Engineering for the appropriate retrofit GH model number, or if you have questions.
Contact MTS Applications Engineering for the appropriate retrofit GH model number, or if you have questions.	

#### Table D

GH Model	•	Installing 6-pin MS female connect	tor, part no. 370015
Integral Wire Color Code	Output for "Square Wave" Neuter (Using "+Stop")	For "R1" connection type: (positive interrogation)	For "R2" connection type: (negative interrogation)
Gray	(-) Stop	No Connection (note 1)	No Connection (note 1)
Pink	(+) Stop (Compatible Neuter Output Pulse)	С	C
Yellow	(+) Start	E	B (note 2)
Green	(-) Start	B (note 2)	E
Red or Brown	Supply Voltage (+Vdc)	F	F
White	DC Ground (for supply)	В	В

Notes:

1. The G-Series output signal, "(-) Stop", is not used when providing the backwards-compatible neuter type connection. However, this signal wire is required for "RS-422 TX --" during serial programming of the sensor. Pin A of the 370015 connector can not be used for this signal since the Analog Output Module (AOM), or the Digital Interface Box (DIB), provides +12 to +14.5 volts output on this pin when connected. Upon installing the 370015 connector the gray wire must be left disconnected, and the serial programming feature of the sensor is no longer available.

2. When connecting to an AOM, or to a DIB, or to a custom interface/controller that requires single-ended interrogation, always connect the unused interrogation lead to ground.

#### Table E

GH Model		Installing 10-pin MS male connector, part no. 370160
Integral Wire Color Code	Digital pulse Output	Pin No.
Gray	<ul><li>(-) Gate for PWM</li><li>(-) Stop for Start/Stop</li></ul>	К
Pink	<ul><li>(+) Gate for PWM</li><li>(+) Stop for Start/Stop</li></ul>	G
Yellow	<ul><li>(+) Interrogation for PWM (note 1)</li><li>(+) Start for Start/Stop</li></ul>	E
Green	(-) Interrogation for PWM (note 1) (-) Start for Start/Stop	D
Red or Brown	Supply Voltage (+Vdc)	Н
White	DC Ground (for supply)	A

Note:

1. When using PWM output with internal interrogation, both of the interrogation input signals are not used, and can be left unconnected or connected to ground.

## Table F

HO Cable Connections for Ana	log Output		GH Model			
Wire color Twisted Pair	Wire Color	Analog output	Wire Color	Analog output		
White/Black	White	Displacement Out	Gray	-10 to +10 Vdc or reverse acting: +10 to -10 Vdc		
	Black	Displacement Return	Pink	Return for Gray Wire		
Red/Black	Red	+15 Vdc	Red or Brown	Supply Voltage (+Vdc)		
neu/ diack	Black	DC Ground	White	DC Ground (for supply)		
Yellow/Black	Yellow	-15 Vdc	N/A	No Connection		
reliuw/black	Black	Frame	N/A	No Connection		
Green/Black	Green	Not used	N/A	No Connection		
GIEEII/DIACK	Black	Not used	N/A	No Connection		
Blue/Black	Blue	Not used	Yellow	Programming (RS-485 +)		
DIUE/DIACK	Black	Not used	Green	Programming (RS-485 -)		

# Table G

HO Cable connections for d	ligital-pulse ou	ıtput	GH Model	
Wire color twisted pair	Wire color	Digital-pulse output	Wire color	Digital-pulse output
White/Black	White	+ Gate	Pink	(+) Gate for PWM (+) Stop for Start/Stop, or Programming (RS-422 TX+)
WITTE, DIACK	Black	-Gate	Gray	(-) Gate for PWM (-) Stop for Start/Stop, or Programming (RS-422 TX-)
Red/Black	Red	+15 Vdc	Red or Brown	Supply voltage (+Vdc)
Indu/ Diack	Black	DC Ground	White	DC ground (for supply)
Yellow/Black	Yellow	-15 Vdc	N/A	No connection
TEIIUW/DIACK	Black	Frame	N/A	No connection
Green/Black	Green	Not used	N/A	No connection
GIEEII/DIACK	Black	Not used	N/A	No connection
Blue/Black	Blue	+ Interrogate	Yellow	<ul> <li>(+) Interrogation for PWM</li> <li>(+) Start for Start/Stop, or Programming (RS-422 RX +)</li> </ul>
DIUE/DIACK	Black	- Interrogate	Green	(-) Interrogation for PWM (-) Start for Start/Stop, or Programming (RS-422 RX -)

Table H				
HO Cable connections for neuter output			GH Model	
Wire color twisted pair	Wire color	Neuter output	Wire color	Neuter output (Note 1)
White/Black	White	Not used	N/A	No connection
	Black	Not used	Gray	(-) Stop (note 2), or Programming (RS-422 TX -)
Red/Black	Red	+15 Vdc	Red or Brown	Supply voltage (+Vdc)
	Black	DC Ground	White	DC ground (for supply)
Yellow/Black	Yellow	-15 Vdc	N/A	No connection
	Black	Frame	N/A	No connection
Green/Black	Green	Output pulse	Pink	(+) Stop (Compatible Neuter output pulse), or programming (RS-422 TX +)
	Black	Not used	N/A	No connection
Blue/Black	Blue	+ Interrogate	Yellow	(+) Start (notes 3 & 4), or programming (RS-422 RX +)
	Black	- Interrogate	Green	(-) Start (Notes 3 & 4) or Programming (RS-422 RX -)

#### Notes:

1. The "(+) Stop" output is used for a compatible square wave neuter signal.

 The G-Series output signal, "(-) Stop" is not used when providing the backwards-compatible neuter type connection. However, this signal wire/connector pin is used for "RS-422 TX-" during serial programming of the sensor. When the sensor output is active, (not in programming mode), this signal must be left unconnected to allow the proper neuter type output.

3. When connecting to an Analog Output Module (AOM), or to a Digital Interface Box (DIB), or to a custom interface/controller that requires single-ended interrogation, always connect the unused interrogation lead, "(+) Start" or "(-) Start", to ground at the AOM/DIB/Controller.

4. For improved noise rejection when using external interrogation, use the positive and negative interrogation signals, "(+) Start" and "(-) Start", to provide differential inputs to the sensor.



Part Number: 06-04 550967 Revision A Temposonics is a registered trademark of MTS Systems Corporation. All other trademarks are the property of their respective owners. All Temposonics sensors are covered by US patent number 5,545,984. Additional patents are pending. Printed in USA. Copyright © 2004 MTS Systems Corporation. All Rights Reserved.



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