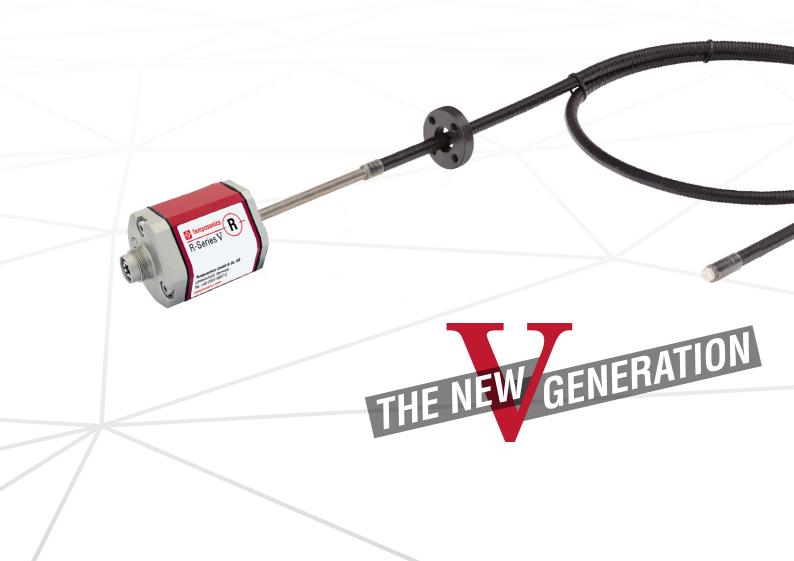


Data Sheet

R-Series V RFV Analog Magnetostrictive Linear Position Sensors

- Flexible sensor rod
- Stroke length up to 20 m
- Field adjustments and diagnostics using the new TempoLink[®] smart assistant



MEASURING TECHNOLOGY

The absolute, linear position sensors provided by Temposonics rely on the company's proprietary magnetostrictive technology, which can determine position with a high level of precision and robustness. Each Temposonics position sensor consists of a ferromagnetic waveguide, a position magnet, a strain pulse converter and a supporting electronics. The magnet, connected to the object in motion in the application, generates a magnetic field at its location on the waveguide. A short current pulse is applied to the waveguide. This creates a momentary radial magnetic field and torsional strain on the waveguide. The momentary interaction of the magnetic fields releases a torsional strain pulse that propagates the length of the waveguide. When the ultrasonic wave reaches the beginning of the waveguide it is converted into an electrical signal. Since the speed of the ultrasonic wave in the waveguide is precisely known, the time required to receive the return signal can be converted into a linear position measurement with both high accuracy and repeatability.

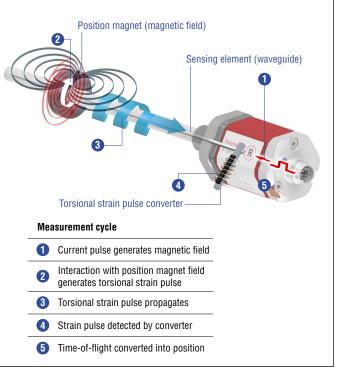


Fig. 1: Time-of-flight based magnetostrictive position sensing principle

R-SERIES V RFV Analog

The Temposonics® R-Series V brings very powerful sensor performance to meet the many demands of your application. The RFV sensor is the R-Series V with flexible rod. The main advantages of the flexible rod are:



Straight and curved line

The flexible measuring rod enables position measurement on straight and also curved line.





Compact for transport and storage For transport and storage, the RFV sensor can be coiled up. This saves costs and space.



Installation with little space

Due to the bendable rod, the RFV sensor can be installed even if only little space is available.



Large stroke length range

The sensor is available with stroke lengths from 150 mm to 20,000 mm and thus can be used in both short and long distance applications.

In addition the R-Series V Analog scores with the following features:



2 positions simultaneously

The R-Series V Analog can detect and report the position of up to 2 magnets simultaneously.



R-Series V Analog

With the R-Series $\widetilde{\mathbf{V}}$ Analog you can configure the Analog output (current/voltage) that it fits best for your application and also adjust it on site with the sensor assistant.

All settings under control with the sensor assistant for the R-Series V The TempoLink® smart assistant supports you in setup and diagnostics of the R-Series V. For more information of the assistant please see the data sheet.

 TempoLink[®] smart assistant (Document part number: 552070)



TECHNICAL DATA

Output					
Analog	Voltage: 010 /100/-10+10/+1010 VDC (min. controller load > 5 kΩ) Current: 4(0)20/204(0) mA (min./max. load 0/500 Ω)				
Measured output variables	Position for one or two position magnets Position + speed (without direction) or velocity (with direction) for one position magnet Position for one position magnet + temperature inside the sensor electronics housing				
Measurement parameters					
Position measurement					
Null/Span adjustment	100 % of electrical stroke				
Resolution	16 bit (internal resolution 0.1 μm)				
Update time	Stroke length ≤ 200 mm ≤ 350 mm ≤ 1200 mm ≤ 2400 mm ≤ 4800 mm ≤ 7620 mm ≤ 10,000 mm ≤ 20,000 mm Update time 0.25 ms 0.333 ms 0.5 ms 1.0 ms 2.0 ms 5.0 ms 7.5 ms 15.0 ms				
Linearity deviation ¹	< ±0.02 % F.S. (minimum ±100 µm)				
Repeatability	$< \pm 0.001$ % F.S. (minimum $\pm 2,5$ µm) typical				
Hysteresis	< 4 μm typical				
Temperature coefficient	< 30 ppm/K typical				
Velocity measurement					
Range	0.0110 m/s or 1400 in./s				
Deviation	≤ 0.05 %				
Resolution	16 bit (minimum 0.01 mm/s)				
Operating conditions					
Operating temperature	-40+85 °C (-40+185 °F)				
Humidity	90 % relative humidity, no condensation				
Ingress protection	IP30 (IP65 rating only for professional mounted guide pipe and if mating connectors are correctly fitted)				
Shock test	100 g/6 ms IEC standard 60068-2-27				
Vibration test	5 g/102000 Hz, IEC standard 60068-2-6 (excluding resonant frequencies)				
EMC test	Electromagnetic emission according to EN 61000-6-3 Electromagnetic immunity according to EN 61000-6-2 The RFV sensors fulfill the requirements of the EMC directives 2014/30/EU, UKSI 2016 No. 1091 and TR CU 020/2011 under the condition of an EMC compliant installation ²				
Magnet movement velocity	Any				
Design/Material					
Sensor electronics housing	Aluminum (painted), zinc die cast				
Sensor flange	Stainless steel 1.4305 (AISI 303)				
Sensor rod	Stainless steel conduit with PTFE coating				
RoHS compliance	The used materials are compliant with the requirements of EU Directive 2011/65/EU and EU Regulation 2015/863 as well as UKSI 2022 No. 622				
Stroke length	15020,000 mm (6787 in.)				
Mechanical mounting					
Mounting position	Any				
Mounting instruction	Please consult the technical drawings on <u>page 5</u> and <u>page 6</u> and the operation manual (document part number: <u>552063</u>)				

Technical data "Electrical connection" on page 4

With position magnet # 251 416-2
 The flexible sensor element must be mounted in an appropriately shielded environment

Electrical connection	
Connection type	$1 \times M16$ male connector (6 pin) or $1 \times M12$ male connector (5 pin) or cable outlet
Operating voltage	1230 VDC ±20 % (9.636 VDC)
Power consumption	< 3.25 W
Dielectric strength	500 VDC (DC ground to machine ground)
Polarity protection	Up to -36 VDC
Overvoltage protection	Up to 36 VDC

TECHNICAL DRAWING

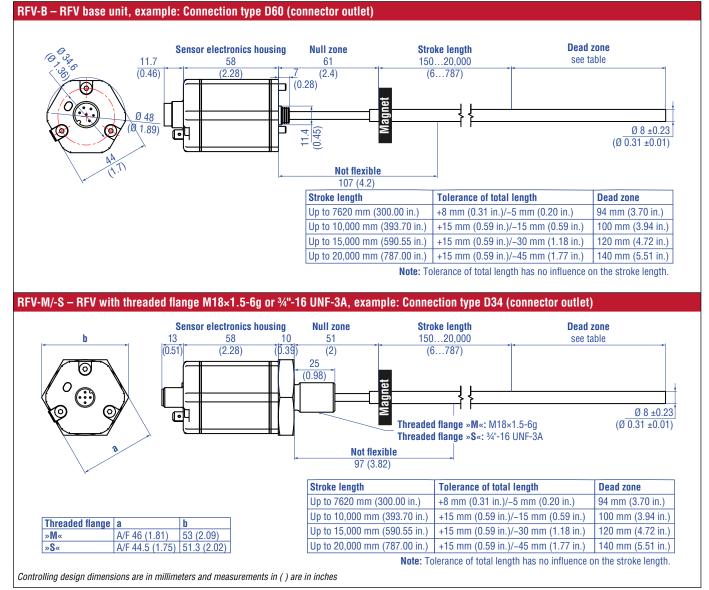


Fig. 2: Temposonics® RFV with ring magnet, part 1

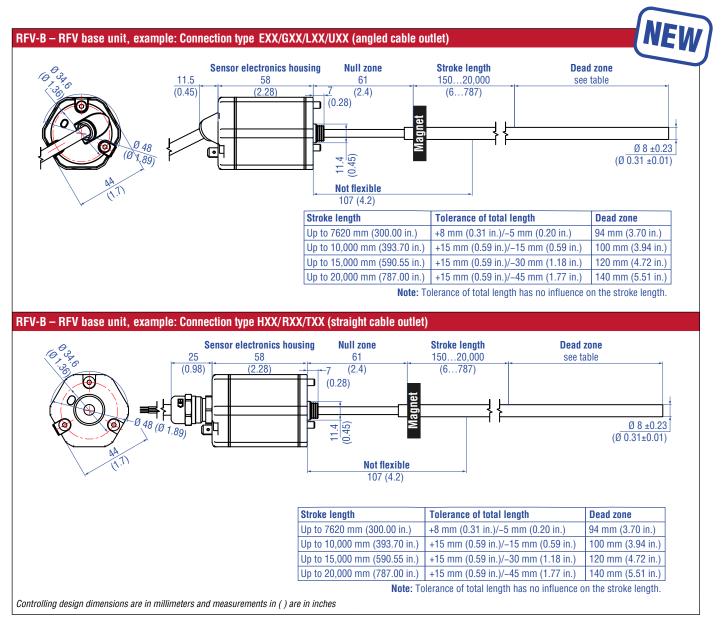


Fig. 3: Temposonics® RFV with ring magnet, part 2

CONNECTOR WIRING

D34					
Signal + power supply					
M12 male connector	Output	Pin	Function		
	1	1	+1230 VDC (±20 %)		
	1	2	Position (magnet 1)		
		3	DC Ground (0 V)		
View on sensor	2*	4	Position (magnet 2) or reverse position (magnet 1) or speed or velocity (magnet 1) or temperature inside the sensor electronics housing		
		5	Signal Ground		
			* order dependent		

Fig. 4: Connector wiring D34

D60						
Signal + power supply						
M16 male connector	Output	Pin	Function			
	4	1	Position (magnet 1)			
		2	Signal Ground			
	2*	3	Position (magnet 2) or reverse position (magnet 1) or speed or velocity (magnet 1) or temperature inside the sensor electronics housing			
View on sensor		4	Signal Ground			
		5	+1230 VDC (±20 %)			
		6	DC Ground (0 V)			
			* order dependent			

Fig. 5: Connector wiring D60

HXX or LXX / RXX or EXX / TXX or GXX / UXX Signal + power supply Cable **Output Color Function** GY Position (magnet 1) 1 PK Signal Ground Position (magnet 2) or reverse position (magnet 1) or speed or velocity (magnet 1) or YE 2* temperature inside the sensor electronics housing GN Signal Ground BN +12...30 VDC (±20 %) WH DC Ground (0 V) * order dependent For cable type TXX, the extra red & blue wires are not used.

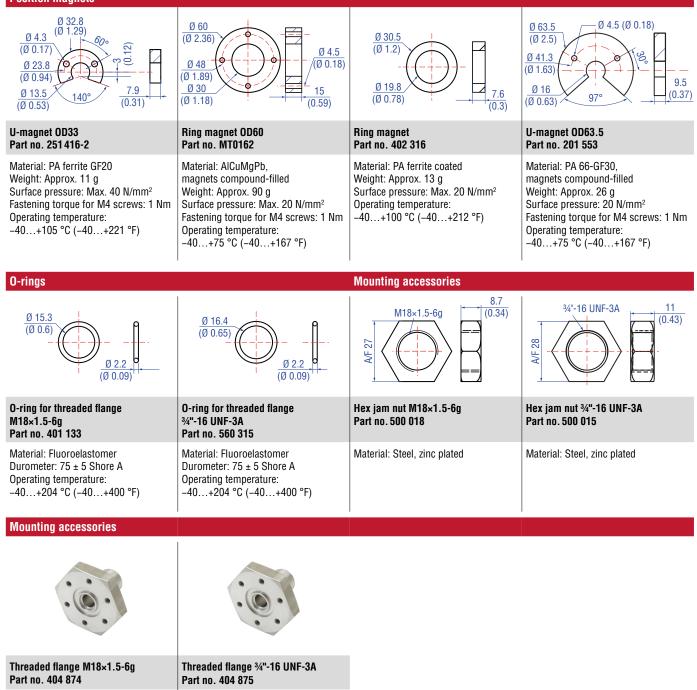
Fig. 6: Connector wiring cable outlet

Str	Straight cable outlet			Cable type Angled cable outlet			le outlet		
Η	X	X	Part no. 530 052	PUR	→	L	X	X	Part no. 530 052
R	X	X	Part no. 530 032	PVC	→	Ε	X	X	Part no. 530 032
Τ	X	X	Part no. 530 112	FEP	→	G	X	X	Part no. 530 157

Fig. 7: Cable types assignment

FREQUENTLY ORDERED ACCESSORIES – Additional options available in our Accessories Catalog 🗍 551444

Position magnets



Material: Stainless steel 1.4305 Material: Stainless steel 1.4305 (AISI 303)

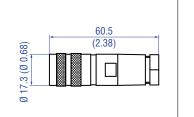
Controlling design dimensions are in millimeters and measurements in () are in inches

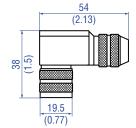
(AISI 303)

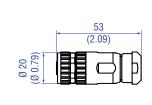
Mounting accessories

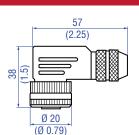
8	63	
Pressure rod with threaded flange with flat-face (M18×1.5-6g) and O-ring HD [length mm: XXXX] M HD [length in.: XXX.X] U	Pressure rod with threaded flange with flat-face (¾"-16 UNF-3A) and O-ring HL [length mm: XXXX] M HL [length in.: XXX.X] U	Profile with flange HFP [length mm: XXXXX] M HFP [length in.: XXXX.X] U
Pressure rod Ø: 12.7 mm (0.5 in.) Length: 1007500 mm (4295 in.) Operating pressure: 350 bar (5076 psi) Material flange: Stainless steel 1.4305 (AISI 303) Material rod: Stainless steel 1.4301 (AISI 304)	Pressure rod Ø: 12.7 mm (0.5 in.) Length: 1007500 mm (4295 in.) Operating pressure: 350 bar (5076 psi) Material flange: Stainless steel 1.4305 (AISI 303) Material rod: Stainless steel 1.4301 (AISI 304)	Length: Max. 20 000 mm (max. 787 in.) Ingress protection: IP30 Material: Aluminum

Cable connectors*









M12 A-coded female connector M16 female connector (6 pin), straight M16 female connector (6 pin), angled M12 A-coded female connector Part no. 370 423 Part no. 370 460 (4 pin/5 pin), straight (5 pin), angled Part no. 370 677 Part no. 370 678 Material: Zinc nickel plated Material: Zinc nickel plated Material: GD-Zn. Ni Material: GD-Zn, Ni Termination: Solder Termination: Solder Termination: Screw Termination: Screw; max. 0.75 mm² Cable Ø: 6...8 mm (0.24...0.31 in.) Cable Ø: 6...8 mm (0.24...0.31 in.) Contact insert: CuZn Contact insert: CuZn Operating temperature: Wire: 0.75 mm² (20 AWG) Cable Ø: 5...8 mm (0.2...0.31 in.) Cable Ø: 4...8 mm (0.16...0.31 in.) -40...+100 °C (-40...+212 °F) Operating temperature: Wire: 1.5 mm² Wire: 0.75 mm² (18 AWG) -40...+95 °C (-40...+203 °F) Ingress protection: IP67 (correctly fitted) Operating temperature: -30...+85 °C (-22...+185 °F) Operating temperature: -25...+85 °C (-13...+185 °F) Ingress protection: IP65/IP67 (correctly fitted) Ingress protection: IP67 (correctly fitted) Fastening torque: 0.6 Nm Fastening torque: 0.6 Nm Ingress protection: IP67 (correctly fitted) Fastening torque: 0.6 Nm Fastening torque: 0.4 Nm

Cables

PVC cable Part no. 530 032	PUR cable Part no. 530 052	FEP cable Part no. 530 112	FEP cable Part no. 530 157
Material: PVC jacket; gray Features: Twisted pair, shielded, flexible Cable Ø: 6 mm (0.23 in.) Cross section: $3 \times 2 \times 0.14 \text{ mm}^2$ Bending radius: $10 \times D$ (fixed installation) Operating temperature: -40+105 °C (-40+221 °F)	Material: PUR jacket; orange Features: Twisted pair, shielded, highly flexible, halogen free, suitable for drag chains, mostly oil & flame resistant Cable Ø: 6.4 mm (0.25 in.) Cross section: $3 \times 2 \times 0.25$ mm ² Bending radius: $5 \times D$ (fixed installation) Operating temperature: -30+80 °C ($-22+176$ °F)	Material: FEP jacket; black Features: Twisted pair, shielded, flexible, high thermal resistance, mostly oil & acid resistant Cable Ø: 7.6 mm (0.3 in.) Cross section: $4 \times 2 \times 0.25$ mm ² Bending radius: $8 - 10 \times D$ (fixed installation) Operating temperature: -100+180 °C ($-148+356$ °F)	Material: FEP jacket; black Features: Twisted pair, shielded Cable Ø: 6.7 mm (0.26 in.) Cross section: 3 × 2 × 0.14 mm ² Operating temperature: -100+180 °C (-148+356 °F)

*/ Follow the manufacturer's mounting instructions

Controlling design dimensions are in millimeters and measurements in () are in inches

Cables	Cable sets	
Silicone cable Part no. 530 176	Cable with M12 A-coded female connector (5 pin), straight – pigtail Part no. 370 673	Cable with M12 A-coded female connector (5 pin), angled – pigtail Part no. 370 675
Material: Silicone jacket; black Features: Twisted pair, shielded Cable Ø: 6.3 mm (0.25 in.) Cross section: $3 \times 2 \times 0.14$ mm ² Bending radius: $7 \times D$ (fixed installation) Operating temperature: $-50+150$ °C ($-58+302$ °F)	Material: PUR jacket; black Features: Shielded Cable length: 5 m (16.4 ft) Ingress protection: IP67 (correctly fitted) Operating temperature: -25+80 °C (-13+176 °F)	Material: PUR jacket; black Features: Shielded Cable length: 5 m (16.4 ft) Ingress protection: IP67 (correctly fitted) Operating temperature: -25+80 °C (-13+176 °F)
Programming tools		
Hand programmer for analog output Part no. 253 124	Cabinet programmer for analog output Part no. 253 408	TempoLink® kit for Temposonics® R-Series V Part no. TL-1-0-AD60 (for D60) Part no. TL-1-0-AS00 (for cable outlet) Part no. TL-1-0-AD34 (for D34)
Easy teach-in-setups of stroke length and direction on desired zero/span positions. For sensors with 1 magnet.	Features snap-in mounting on standard DIN rail (35 mm). This programmer can be permanently mounted in a control cabinet and includes a program/run switch. For sensors with 1 magnet.	 Connect wirelessly via Wi-Fi enabled device or via USB with the diagnostic tool Simple connectivity to the sensor via 24 VDC power line (permissible cable length: 30 m) User friendly interface for mobile devices and desktop computers See data sheet "TempoLink[®] smart assistant" (document part no.: 552070) for further information

Controlling design dimensions are in millimeters and measurements in () are in inches Color of connectors and cable jacket may change. Colors of the cores and technical properties remain unchanged.

Temposonics[®] R-Series V RFV Analog Data Sheet

Extension cables

PVC cable with M16 female connector (6 pin), straight – pigtail

PVC cable (part no. 530 032) with M16 female connector, straight (part no. 370 423)

Order code:

K2-A-370423-xxxxyy-530032-0 (where xxxx = cable length and yy = unit in centimeters "CM" or feet "FT")

PUR cable with M16 female connector (6 nin), straight – nigtail

(6 pin), straight – pigtail PUR cable (part no. 530 052) with

M16 female connector, straight (part no. 370 423)

Order code: **K2-A-370423-xxxxyy-530052-0** (where xxxx = cable length and yy = unit in centimeters "CM" or feet "FT")



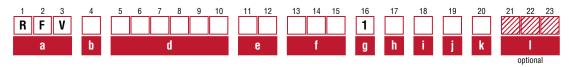
Teflon® cable with M16 female connector (6 pin), straight – pigtail

FEP cable (part no. 530 112) with M16 female connector, straight (part no. 370 423)

Order code: **K2-A-370423-xxxxyy-530112-0** (where xxxx = cable length and yy =

unit in centimeters "CM" or feet "FT")

ORDER CODE



a Sensor model	
R F V Flexible rod	
b Design	
Base unit	
M Threaded flange M18×1.5-6	g (standard)
S Threaded flange ³ / ₄ "-16 UNF	-3A (standard)
Section c is intentionally omi	tted.
d Stroke length	
X X X X X M 00150	20000 mm
Stroke length (mm)	Ordering steps
150 1000 mm	50 mm
1000 5000 mm	100 mm
500010000 mm	250 mm
1000015000 mm	500 mm
1500020000 mm	1000 mm
X X X X X U 0006.0)0787.0 in.
Stroke length (in.)	Ordering steps
6 40 in.	2 in.
40197 in.	4 in.
197394 in.	10 in.
394591 in.	20 in.
591787 in.	40 in.
Non standard stroke lengths are must be encoded in 5 mm/0.1 i	

e Number of magnets

0 X 01...02 Position(s) (1...2 magnet(s))

Cor	nnec	_	stion type
D	3	4	M12 male connector (5 pin)
D	6	0	M16 male connector (6 pin)
Anc	aled	cab	
E	X	X	
G	X	X	XX m/ft. FEP cable (part no. 530 157) G01G30 (130 m/399 ft.) See "Frequently ordered accessories" for cable specifications
L	X	X	XX m/ft. PUR cable (part no. 530 052) L01L30 (130 m/399 ft.) (Note the temperature range of the cable!) See "Frequently ordered accessories" for cable specifications
U	X	X	XX m/ft. Silicone cable (part no. 530 176) U01U30 (130 m/399 ft.) See "Frequently ordered accessories" for cable specifications
Stra	aigh	t ca	ble outlet
Η	X	X	XX m/ft. PUR cable (part no. 530 052) H01H30 (130 m/399 ft.) (Note the temperature range of the cable!) See "Frequently ordered accessories" for cable specifications
R	X		XX m/ft. PVC cable (part no. 530 032) R01R30 (130 m/399 ft.) See "Frequently ordered accessories" for cable specifications
T	X		XX m/ft. FEP cable (part no. 530 112) T01T30 (130 m/399 ft.) See "Frequently ordered accessories" for cable specifications
Enc	ode	in n	neters if using metric stroke length. eet if using US customary stroke length.

g System

1 Standard

h Output

- A Current
- V Voltage

Temposonics[®] R-Series V RFV Analog Data Sheet

Function

- 1 Position (1 or 2 magnets/outputs)
- 2 Position and speed (1 magnet and 2 outputs)
- 3 Position and velocity (1 magnet and 2 outputs)
- 4 Position and reverse position (1 magnet and 2 outputs)
- 5 Position and temperature inside the sensor electronics housing (1 magnet and 2 outputs)
- 6 Differential (2 magnets and 1 output)

j Options

0 Standard

3 Over range output mode

k Output range

- 0 ... 10 VDC or 4... 20 mA
- 1 10...0 VDC or 20...4 mA
- 2 -10...+10 VDC or 0...20 mA
- **3** +10...-10 VDC or 20...0 mA
- V 0...10 VDC for position, -10...+10 VDC for velocity

I Max speed or velocity value

(optional: use when i "Function" is 2 or 3)

For metric stroke lengths encode speed or velocity in m/s for the values 0.01 to 9.99 m/s (001...999) For US customary stroke lengths encode speed or velocity in inches/s for the values 1 to 400 in./s (001...400)

Use the codes (00E) for 0.025 m/s, and (A00) for 10.0 m/s to provide backwards compatibility for these predecessor models of the R-Series.

NOTICE

- Specify the number of magnets for your application and order the magnets separately.
- The number of magnets is limited by the stroke length. The minimum allowed distance between magnets (i.e. front face of one to the front face of the next one) is 75 mm (3 in.).
- Use magnets of the same type for multi-position measurement.

DELIVERY



RFV-M/-S:

- Base unit (without flange & rod assembly) 3 × socket screws M4×59
- Sensor 0-ring

Accessories have to be ordered separately.

Manuals, Software & 3D Models available at: www.temposonics.com

GLOSSARY

A

Analog output

For a sensor with analog output, the measured value is output as an analog voltage signal or current signal.

D

Differential

For differential measurement, the distance between the two position magnets is output as a value.

(→ Multi-position measurement)

М

Max speed or velocity value

For speed or velocity, the output value generated is scaled based on the maximum speed or velocity value indicated in the order code.

Measuring direction

- Forward: Values increasing from sensor electronics housing to rod end/profile end
- Reverse: Values decreasing from sensor electronics housing to rod end/profile end

Multi-position measurement

During the measurement cycle, the positions of every magnet on the sensor are simultaneously reported. The velocity or speed are continuously calculated based on these changing position values as the magnets are moved.

0

Over range output mode

When enabled this mode allows the position output values to continue to increase or decrease when the magnet travels beyond the active stroke range.

R

Resolution

The sensor precisely measures time to provide the position measurement. For the analog output the measured time value is converted into an analog voltage signal or current signal using a high-performance **D**igital to **A**nalog **C**onverter (DAC) having 16 bits of resolution.

S

Speed

The output value for speed indicates how fast the position magnet is being moved, independent of the measuring direction. (\rightarrow Velocity)

T

Temperature inside the sensor electronics housing

The temperature inside the sensor electronics housing is reported as an analog voltage signal or current signal. For each output range, the 0 % output value has the factory default setpoint at -40 °C, and the 100 % output value has the default setpoint at +100 °C. Note: a dedicated temperature chip is used for the output signal and its values may vary from those reported on the TempoLink[®] application screen.

V

Velocity

The output value for velocity indicates how fast the position magnet is being moved, and in which direction. (\rightarrow Speed)



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