

Temposonics®

Absolute, Non-Contact Position Sensors

Data Sheet R-Series Analog

Temposonics® RP and RH
Stroke length 50...7600 mm



100% field adjustable Null and Span

- Rugged industrial sensor
- Linear and absolute measurement
- LEDs for sensor diagnostics
- Non-contact sensing with highest durability
- Superior accuracy: Linearity better 0.01 % F.S.
- Repeatability 0.001 % F.S.
- Direct analog output, position + speed
- Dual magnet position measurement

Sensor diagnostic display

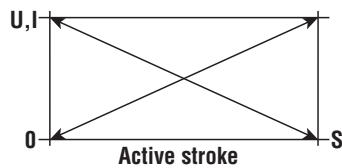
Integrated LEDs (green/red) provide basic visual feedback for normal sensor operation and troubleshooting.



| Green | Red | Description |
|----------|----------|---|
| ON | OFF | Normal function |
| ON | ON | Magnet not detected, Wrong quantity of magnets |
| ON | Flashing | Magnet out of setup range |
| Flashing | ON | Programming mode |

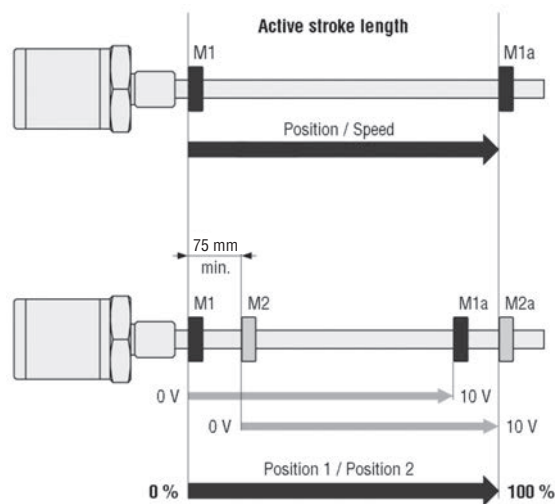
Output

Smart analog sensors provide direct analog outputs including voltage and current. All outputs allow 100 % adjustments of zero and span setpoints. Since the outputs are direct, no signal conditioning electronics are needed when interfacing with controllers or meters.



Availability

- Single magnet sensor provides one position output over the entire active stroke length and one velocity output with 1 magnet.
- Dual magnets sensor provides two identical positions outputs; a separate output is provided for each of two magnets positioned along sensor length.



Sensor field programming

Temposonics® R-Series sensors are preconfigured at the factory by model code designation. If needed, MTS offers different external service tools for modifying sensor parameters inside the **active electrical stroke** (minimum 25 mm between setpoints) via the standard connection cable. There is no need to open the sensors electronics. Following tools are available:

1. Hand-Programmer R-Analog for 1 magnet sensor

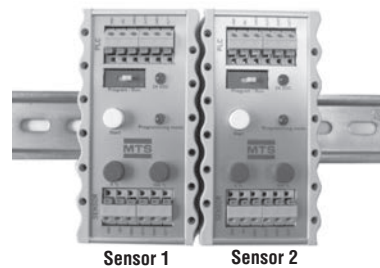
for easy teach-in setups of stroke length and direction by moving the magnet on desired Null/Span positions and pushing the 0/100 % buttons.



Hand-Programmer R-Analog, part no. 253 124

2. Cabinet-Programmer R-Analog

Cabinet-Programmer R-Analog completes the accessories program of MTS absolute position sensors. The unit can be used for adjusting a connected 1-magnet sensor via the leads, using a simple teach-in procedure in the field.



Cabinet-Programmer R-Analog, part no. 253 408

10 x 55 x 31 mm

3. USB-Programmer R-Analog for 1 or 2 magnet's sensors

This hardware converter is required to communicate via USB-port of a Windows PC to the sensor. Customized settings are possible by using the MTS programming software (CD-ROM) for:

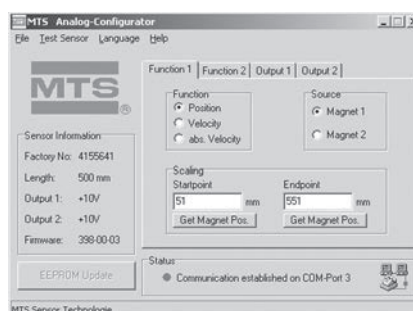
- Zero/Span Magnet 1
- Zero/Span Magnet 2
- Velocity range
- Free assignment of outputs to measured position or velocity
- Error output value (e.g. magnet out of stroke)



Programming kit, part no. 253 134-1

(PC-Programmer, power supply, USB-cable, sensor-cable, software)

Windows sensor programming



Technical Data

Input

| | |
|----------------|--|
| Measured value | Position, velocity / dual magnet position measurements |
| Stroke length | Profile: 50...5000 mm, Rod: 50...7600 mm |

Output

| | |
|---------|---|
| Voltage | 0...10 / 10...0 / -10...+10 / +10...-10 VDC (min. load controller: > 5 kOhms) |
| Current | 4(0)...20 mA / 20...4(0) mA (min/max. load: 0/500 Ohms) |

Accuracy

| | |
|-------------------------|---|
| Position measurement: | |
| - Null/Span adjustment | 100 % of electrical stroke (min. range 25 mm) |
| - Resolution | 16 bit; 0.0015 % (Minimum 1 µm) |
| - Linearity | < ± 0.01 % F.S. (Minimum ± 50 µm) |
| - Repeatability | < ± 0.001 % F.S. (Minimum ± 1 µm) |
| - Hysteresis | < 4 µm |
| - Update time | 0.5 ms up to 1200 mm / 1.0 ms up to 2400 mm / 2.0 ms up to 4800 mm / 5.0 ms up to 7600 mm stroke length |
| - Ripple | < 0.01 % F.S. |
| Velocity measurement: | |
| - Range | 0.025 - 10 m/s |
| - Deviation | < 0.5 % |
| - Resolution | 0.1 mm/s Option 0.01 mm/s |
| - Update time (ms) | see position measurement |
| Temperature coefficient | < 30 ppm/°C |

Operating conditions

| | |
|---------------------------------|--|
| Magnet speed | any |
| Operating temperature | -40 °C...+75 °C |
| Dew point, humidity | 90% rel. humidity, no condensation |
| Ingress protection ¹ | Profile: IP65, Rod: IP67, IP68 for cable outlet, RS: IP69K |
| Shock test | 100 g single hit, IEC-Standard 60068-2-27 |
| Vibration test | 15 g / 10 - 2000 Hz, IEC-Standard 60068-2-6 |
| Standards, EMC test | Electromagnetic emission EN 61000-6-4 Electromagnetic immunity EN 61000-6-2 EN 61000-4-2/3/4/6, Level 3, Criterion A, CE-qualified |

Design, material

| | |
|--------------------|---|
| Diagnostic display | LEDs beside connector |
| Profile model: | |
| Sensor head | Aluminum |
| Sensor stroke | Aluminum |
| Position magnet | Magnet slider or removable U-magnet |
| Rod model: | |
| Sensor head | Aluminum |
| Rod with flange | Stainless steel 1.4301 / AISI 304 |
| Pressure rating | 350 bar, (700 bar peak) for hydraulic rod |
| Position magnet | Ring magnets, U-magnets |

Installation

| | |
|---------------------|---|
| Mounting position | any orientation |
| Profile | Movable mounting clamps fixed with M5 x 20 screws or T-slot nuts M5 in base channel |
| U-magnet, removable | Mounting plate and screws from antimagnetical material |
| Rod | Threaded flange M18 x 1.5 or 3/4" -16 UNF-3A, Hex nut M18 |
| Position magnet | Mounting plate and screws from antimagnetical material |

Electrical connection

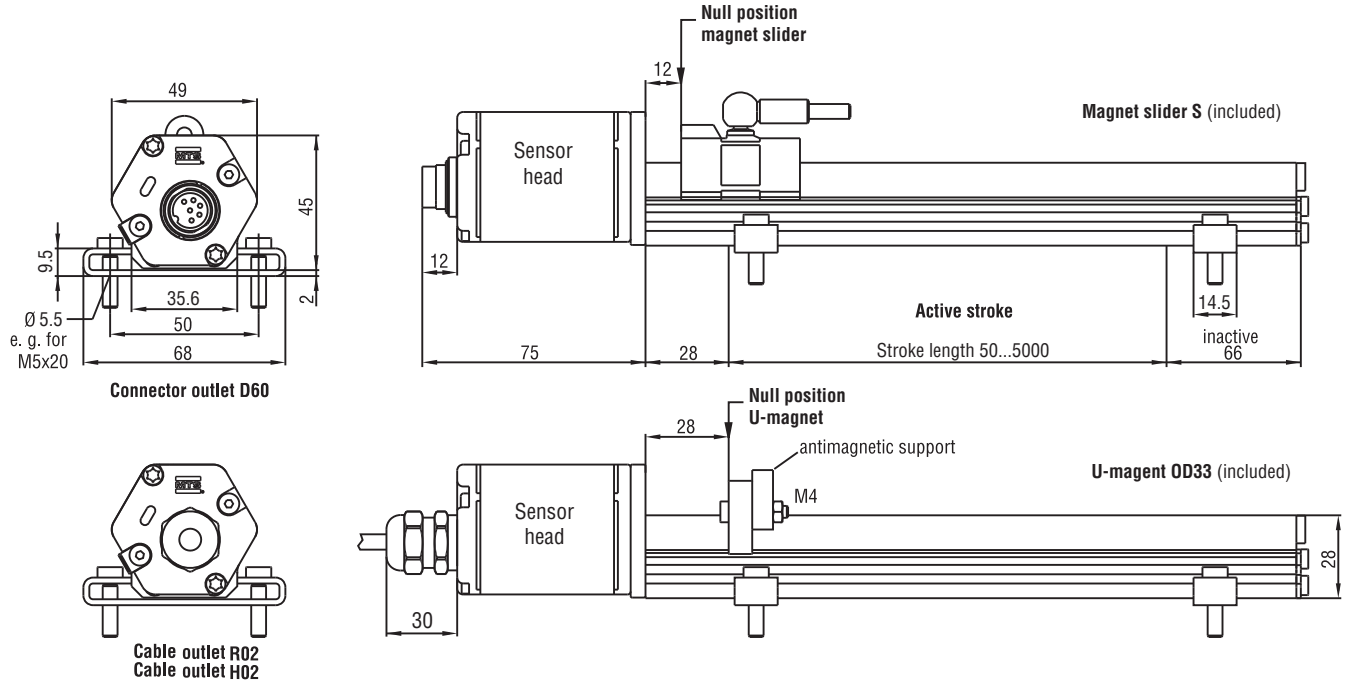
| | |
|--------------------------|---|
| Connection type | 6 pin connector M16 or cable outlet |
| Supply voltage | 24 VDC (-15 / +20 %); UL Recognition requires an approved power supply with energy limitation (UL 61010-1), or Class 2 rating according to the National Electrical Code (USA) / Canadian Electrical Code. |
| - Polarity protection | up to -30 VDC |
| - Overvoltage protection | up to 36 VDC |
| Current drain | 100 mA typical |
| Ripple | ≤ 0.28 Vpp |
| Electric strength | 500 VDC (DC ground to machine ground) |


¹ The IP rating is not part of the UL recognition

Stable profile design

Temposonics® RP offers modular construction, flexible mounting configurations and easy installation. Position measurement is contactless via two versions of permanent magnets.

- A sliding magnet running in profile housing rails. Connection with the mobile machine part is via a ball jointed arm to taking up axial forces.
- A floating magnet, mounted directly on the moving machine part, travels over the profile at a low distance. Its air-gap allows the correction of small misalignments at installation.



| Wiring | Pin | Cable | Function |
|--|-----|--------|---|
|  <p>Male insert sensor plug rear of cable connector</p> | 1 | grey | Output 1: Position #1 0...10/10...0/-10...+10/+10...-10 V 4(0)...20/20...4(0) mA |
| | 2 | pink | DC Ground |
| | 3 | yellow | Output 2: Position #2 or velocity 0...10/10...0/-10...+10/+10...-10 V 4...20/20...4 mA |
| | 4 | green | DC Ground |
| | 5 | brown | +24 VDC (-15/+20 %) |
| | 6 | white | DC Ground (0 V) |

All dimensions in mm

Standard position magnet included in delivery (see chapter accessories)

Position magnets

Magnet slider S (part no. 252 182)
Magnet slider V (part no. 252 184)
U-magnet OD33 (part no. 251 416-2)

Connection types

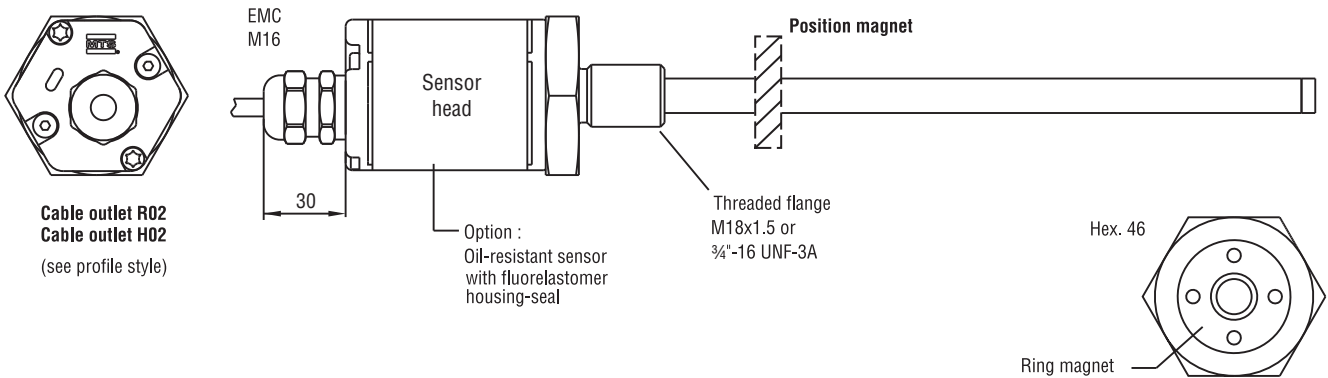
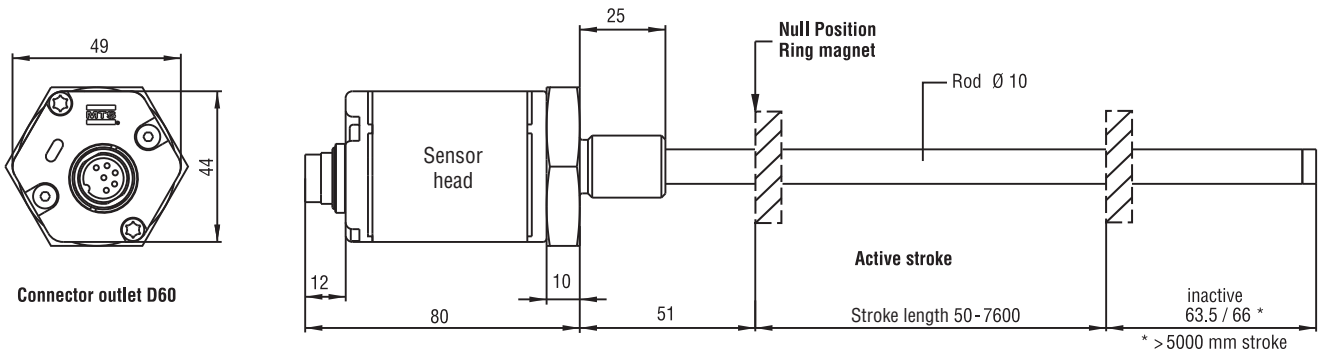
6 pin female connector (part no. 370 623)
6 pin female connector M16, 90° (part no. 370 460)

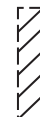
High pressure rod design

Temposonics® RH with a pressure-resistant stainless steel flange and sensing rod is suitable for use in hydraulic cylinders and externally in all applications where space is a problem. Position measurement is via ring or U-magnets travelling along the sensing rod without any mechanical contact.

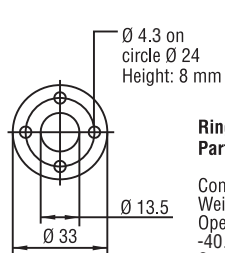
Advantage

the completely operable sensor cartridge can be replaced for servicing easily without opening the fluid circuit.



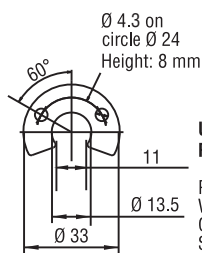
 = Magnets must be ordered separately (details see chapter accessories)

Standard position magnets (not included in delivery, please order separately)



Ring magnet OD33
Part No. 201 542-2

Composite PA-Ferrite-GF20
Weigh ca. 14 g
Operating temperature:
-40...+100 °C
Surface pressure max. 40 N/mm²
Fastening Torque for M4 screws max. 1 Nm



U-magnet OD33
Part No. 251 416-2

PA-Ferrit-GF20
Weigh ca. 11 g
Operating temperature: -40...+100 °C
Surface pressure max. 40 N/mm²
Fastening torque for M4 screws max. 1 Nm

All dimensions in mm

Standard position magnet not included in delivery (see chapter accessories)

Position magnets

Ring magnet OD33 (part no. 201 542-2)
Ring magnet OD25,4 (part no. 400 533)
U-magnet OD33 (part no. 251 416-2)

Connection types

6 pin female connector (part no. 370 623)
6 pin female connector M16, 90° (part no. 370 460)

Temposonics®

Sensor model

RP - Profile
RH - Hydraulic rod

Design

Profile Temposonics® RP:

S - Magnet slider, joint at top
V - Magnet slider, joint at front
M - U-magnet, OD33

Rod Temposonics® RH:

M - Flange M18 x 1.5 (Standard)
V - Flange M18 x 1.5 (Fluorelastomer housing-seal)
D - Flange M18 x 1.5 with bushing on rod end
R - Flange M18 x 1.5 with thread M4 at rod end
J - Flange M22 x 1.5, rod Ø 12.7 mm, 800 bar
S - Flange ¾" - 16 UNF - 3A

Stroke length

Profile - 0050...5000 mm

Rod - 0050...7600 mm

Standard: See chart

Other length upon request.

Connection type

D60 - 6 pin male receptacle M16

R02 - 2 m PVC cable w/o connector, Option: R01-R10 (1 - 10 m)

H02 - 2 m PUR cable w/o connector, Option: H01-H10 (1 - 10 m)

Supply voltage

1 - +24 VDC

A - +24 VDC, high vibration resistant (stroke length 25...2000 mm)

Output

1 Output with 1 magnet

Output 1 (position magnet 1)

V01 = 0...10 VDC A01 = 4...20 mA

V11 = 10...0 VDC A11 = 20...4 mA

V21 = -10...+10 VDC A21 = 0...20 mA

V31 = +10...-10 VDC A31 = 20...0 mA

2 Outputs with 2 magnets

Output 1 (position magnet 1) + Output 2 (position magnet 2)

V02 = 0...10 VDC 0...10 VDC

V12 = 10...0 VDC 10...0 VDC

V22 = -10...+10 VDC -10...+10 VDC

V32 = +10...-10 VDC +10...-10 VDC

A02 = 4...20 mA 4...20 mA

2 Outputs with 1 magnet

Output 1 (position magnet 1) + Output 2 (absolute speed magnet 1)

Magnet direction >>>>> Head Null Tip

V01 xxx.x = 0...10 VDC +10.....0.....+10 VDC

V11 xxx.x = 10...0 VDC +10.....0.....+10 VDC

A01 xxx.x = 4...20 mA 20.....4..... 20 mA

A11 xxx.x = 20...4 mA 20.....4..... 20 mA

Output 1 (position magnet 1) + Output 2 (speed magnet 1)

Magnet direction >>>>> Head Null Tip

V61 xxx.x = 0...10 VDC -10.....0.....+10 VDC

V71 xxx.x = 10...0 VDC +10.....0.....-10 VDC

A41 xxx.x = 4...20 mA 4.....12..... 20 mA

Output 1 (position magnet 1) + Output 2 (position magnet 1)

V03 = 0...10 VDC 10...0 VDC

Output 1 (position magnet 1) + Output 2 (electronics temperature)

A04 = 4...20 mA 4...20 mA (-40°C...+100°C)

3 / 7 digits

Included in delivery profile model:

Sensor, Position magnet, 2 mounting clamps up to 1250 mm + 1 clamp for every additional 500 mm

Included in delivery rod model:

Sensor and O-ring.
Magnets must be ordered separately.

| Stroke Length Standard RP | |
|---------------------------|----------------|
| Stroke length | Ordering steps |
| ≤ 500 mm | 25 mm |
| 500...2500 mm | 50 mm |
| 2500...5000 mm | 100 mm |

| Stroke Length Standard RH | |
|---------------------------|----------------|
| Stroke length | Ordering steps |
| < 500 mm | 5 mm |
| 500...750 mm | 10 mm |
| 750...1000 mm | 25 mm |
| 1000...2500 mm | 50 mm |
| 2500...5000 mm | 100 mm |
| > 5000 mm | 250 mm |

Fill in blanks (xxxx) with desired max. speed (see above):

- Speed range 1: 0.1...10 m/s (0001...0100)

Sample: (-5.5...0...5.5 m/s = 10...0...10 VDC) = V01 0055

- Speed range 2: 25...90 mm/s (1025...1090)

Sample: (-50...0...50 mm/s = 4...12...20 mA) = A41 1050

Accessories page 67 and following.

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