

Data Sheet

R-Series V RM5 SSI

Magnetostrictive Linear Position Sensors

- Super shield housing with IP68/IP69 against ingress of dust and water
- Position measurement with a resolution up to 0.1 μm
- Update rate up to 10 kHz



V
THE NEW GENERATION

MEASURING TECHNOLOGY

The absolute, linear position sensors provided by Temposonics rely on the company's proprietary magnetostrictive technology, which can determine position with a high level of precision and robustness. Each Temposonics® position sensor consists of a ferromagnetic waveguide, a position magnet, a strain pulse converter and a supporting electronics. The magnet, connected to the object in motion in the application, generates a magnetic field at its location on the waveguide. A short current pulse is applied to the waveguide. This creates a momentary radial magnetic field and torsional strain on the waveguide. The momentary interaction of the magnetic fields releases a torsional strain pulse that propagates the length of the waveguide. When the ultrasonic wave reaches the beginning of the waveguide it is converted into an electrical signal. Since the speed of the ultrasonic wave in the waveguide is precisely known, the time required to receive the return signal can be converted into a linear position measurement with both high accuracy and repeatability.

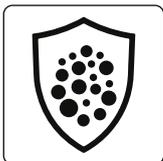
R-SERIES V RM5 SSI

The Temposonics® R-Series V brings very powerful sensor performance to meet the many demands of your application. The RM5 sensor is the version of the RH5 rod sensor in a protective housing (super shield housing). The main advantages of the RM5 are:



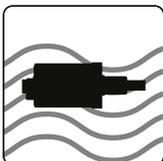
Protection against corrosion

The housing made of high-quality stainless steel offers very good corrosion resistance. Thus, you can use the R-Series V also in aggressive environments.



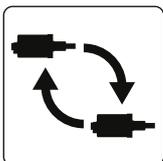
Protection against ingress of dust

The housing protects the internal sensor against penetration of dust. This maintains the sensor's performance even in heavy dust.



Protection against ingress of water

The housing protects the internal sensor when submerged. This allows you to use the R-Series V even under water.



Easy and fast replacement

If necessary, the sensor inside the housing can be replaced easily and fast. This saves time and downtime costs.

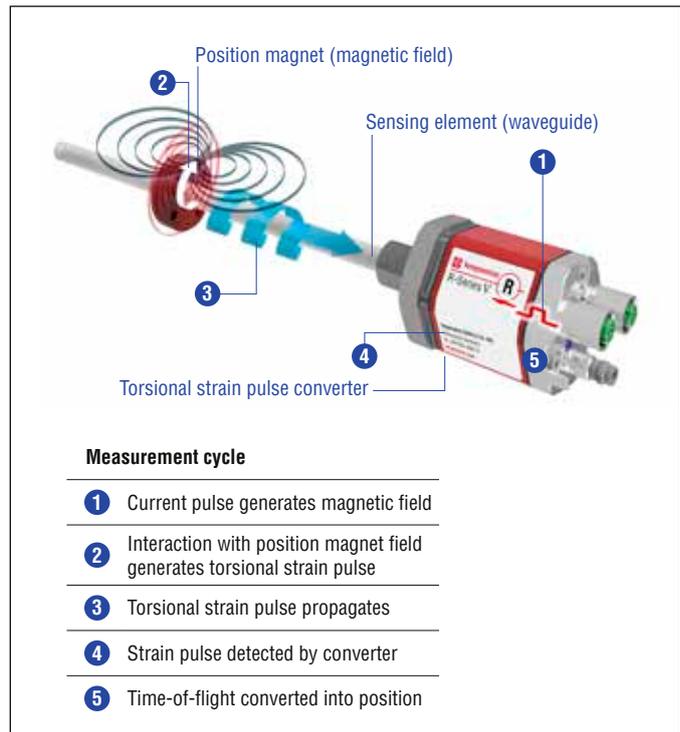
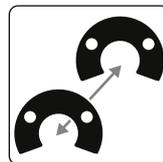


Fig. 1: Time-of-flight based magnetostrictive position sensing principle

In addition the R-Series V SSI scores with the following features:



Differential measurement between 2 positions

The R-Series V SSI can measure and output the distance between 2 position magnets.



R-Series V SSI

The interface of the R-Series V SSI corresponds to the SSI industry standard for absolute encoders. You can select the configuration of the SSI signal that fits best to your application and also adjust it on site with the sensor assistants.

All settings under control with the sensor assistants for the R-Series V

The TempoLink® and the TempoGate® smart assistants support you in setup and diagnostics of the R-Series V. For more information of these assistants please see the data sheets:

- TempoLink® smart assistant (Document part number: [552070](#))
- TempoGate® smart assistant (Document part number: [552110](#))



TECHNICAL DATA

Output							
Interface	SSI (Synchronous Serial Interface) – differential signal in SSI standard (RS-485/RS-422)						
Data format	Binary or gray						
Data length	8...32 bit						
Data transmission rate	70 kBaud ¹ ...1 MBaud, depending on cable length:						
	Cable length	< 3 m	< 50 m	< 100 m	< 200 m	< 400 m	
	Baud rate	1 MBd	< 400 kBd	< 300 kBd	< 200 kBd	< 100 kBd	
Measured value	Position or velocity, position and temperature in the sensor electronics housing						
Measurement parameters							
Resolution: Position	0.1...100 µm (0.0001...0.1 mm)						
Resolution: Velocity	0.001 mm/s (determined over 10 measured values)						
Update rate ²	Stroke length	25 mm	300 mm	750 mm	1000 mm	2000 mm	7615 mm
	Update rate	10 kHz	3.4 kHz	2.7 kHz	2.1 kHz	1.2 kHz	0.3 kHz
Linearity deviation ³	Stroke length	≤ 400 mm	> 400 mm				
	Linearity deviation	≤ ±40 µm	< ±0.01 % F.S.				
	Optional internal linearization: Linearity tolerance (applies for the first magnet for differential measurement)						
	Stroke length	25...300 mm	300...600 mm	600...1200 mm			
		typical	± 15 µm	± 20 µm	± 25 µm		
		maximum	± 25 µm	± 30 µm	± 50 µm		
Repeatability	< ±0.001 % F.S. (minimum ±2.5 µm) typical						
Hysteresis	< 4 µm typical						
Temperature coefficient	< 15 ppm/K typical						
Operating conditions							
Operating temperature	-40...+85 °C (-40...+185 °F)						
Humidity	100 % relative humidity, no condensation						
Ingress protection	IP68 (3 m/180 d)/IP69						
Shock test	100 g/6 ms, IEC standard 60068-2-27						
Vibration test	10 g/10...2000 Hz, IEC 60068-2-6 (excluding resonant frequencies)						
EMC test	Electromagnetic emission according to EN 61000-6-3						
	Electromagnetic immunity according to EN 61000-6-2						
	The RM5 sensors fulfill the requirements of the EMC directives 2014/30/EU, UKSI 2016 No. 1091 and TR CU 020/2011						
Operating pressure	350 bar (5076 psi)/700 bar (10,153 psi) peak (at 10 × 1 min) for sensor rod						
Magnet movement velocity	Any						
Design/Material							
Sensor electronics housing	Stainless steel 1.4404 (AISI 316L)						
Sensor flange	Stainless steel 1.4404 (AISI 316L)						
Sensor rod	Stainless steel 1.4404 (AISI 316L)						
RoHS compliance	The used materials are compliant with the requirements of EU directive 2011/65/EU and EU regulation 2015/863 as well as UKSI 2022 No. 622						
Stroke length	25...7615 mm (1...299.8 in.)						

Technical data “Mechanical mounting” and “Electrical connection” on [page 4](#)

1/ With standard one shot of 16 µs

2/ Sensor with standard settings. Further information can be found in the operation manual R-Series V SSI (document part number: [552011](#))

3/ With position magnet # 251 416-2

Temposonics® R-Series V RM5 SSI

Data Sheet

Mechanical mounting	
Mounting position	Any
Mounting instruction	Please consult the technical drawings and the operation manual (document number: 552011)
Electrical connection	
Connection type	Cable outlet
Operating voltage	+12...30 VDC \pm 20 % (9.6...36 VDC)
Power consumption	1.2 W typical
Dielectric strength	500 VDC (DC ground to machine ground)
Polarity protection	Up to -36 VDC
Overvoltage protection	Up to 36 VDC

TECHNICAL DRAWING

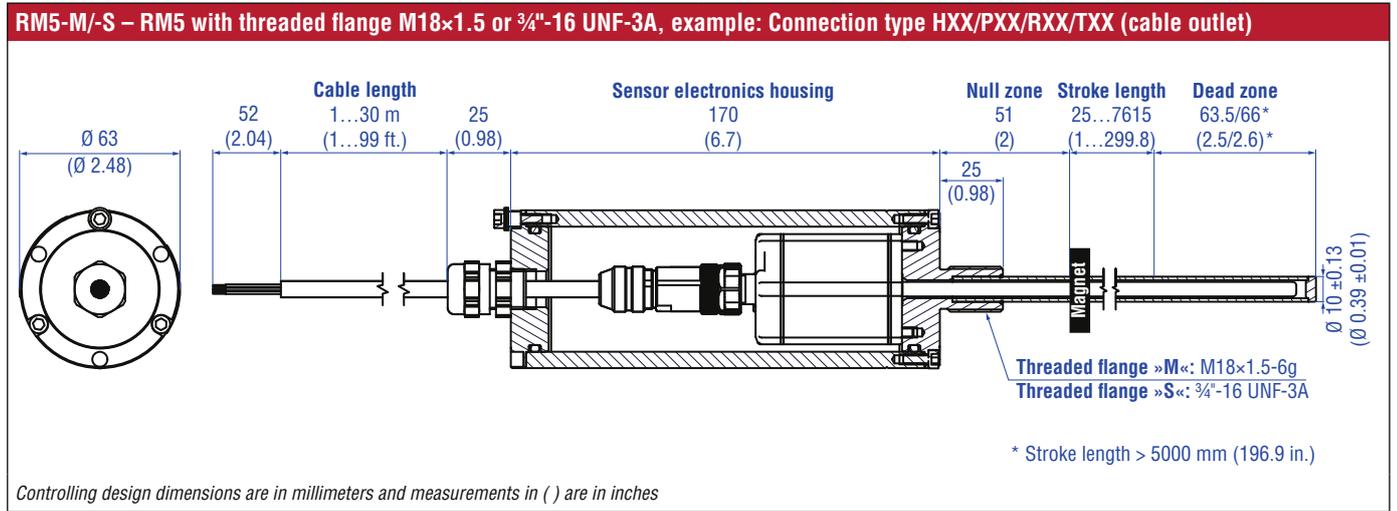


Fig. 2: Temposonics® RM5 with ring magnet

STRUCTURE

The RM5 SSI consists of (Fig. 3)

- 1 Super shield housing
- 2 R-Series V sensor with connector outlet (connection type D84)
- 3 Cable for direct connection to the controller (connection type HXX/PXX/RXX/TXX)

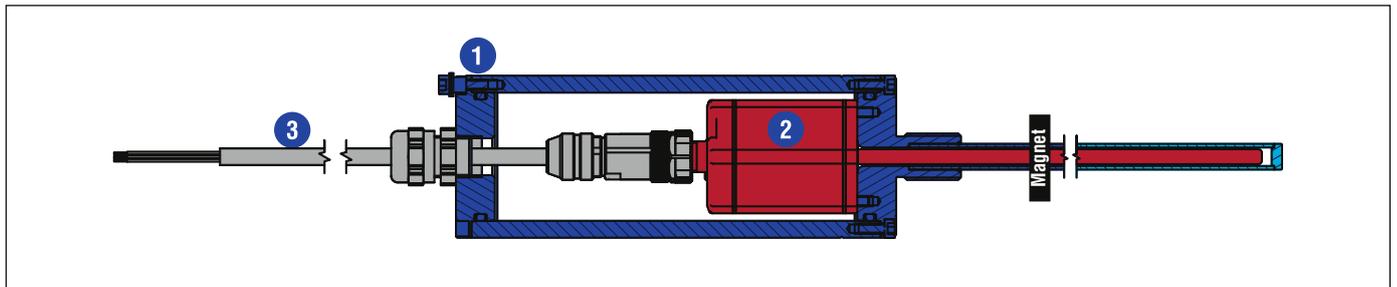
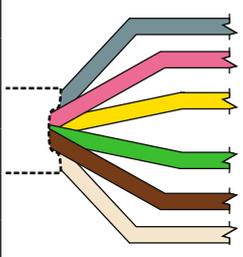


Fig. 3: Structure of RM5 SSI

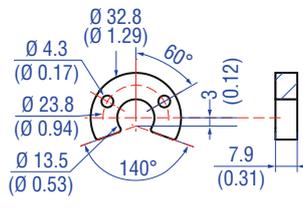
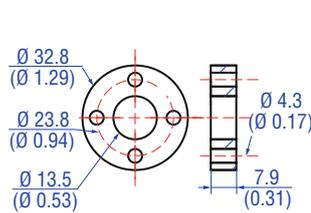
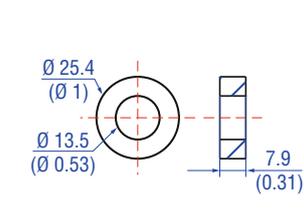
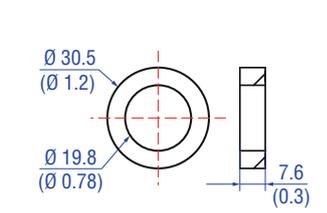
CONNECTOR WIRING

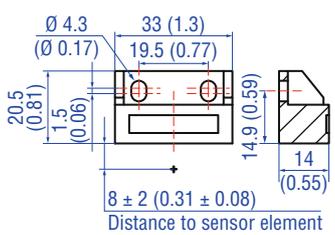
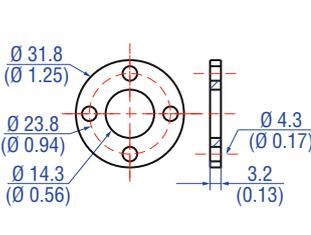
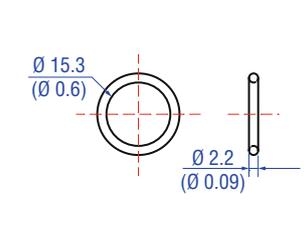
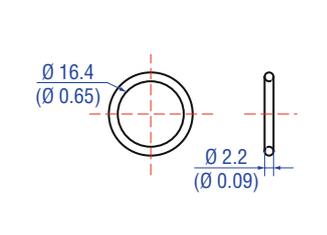
HXX/PXX/RXX/TXX		
Signal + power supply		
Cable	Color	Function
	GY	Data (-)
	PK	Data (+)
	YE	Clock (+)
	GN	Clock (-)
	BN	+12...30 VDC ($\pm 20\%$)
	WH	DC Ground (0 V)

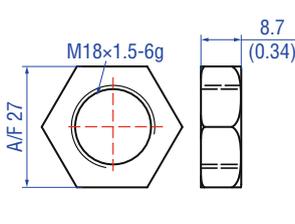
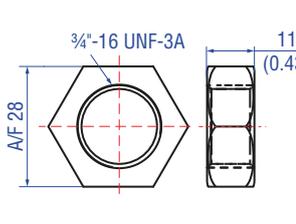
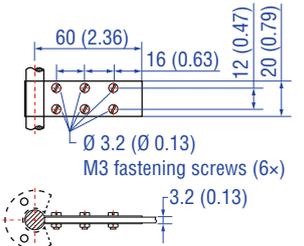
For cable type TXX, the extra red & blue wires are not used.

Fig. 4: Connector wiring HXX/PXX/RXX/TXX

FREQUENTLY ORDERED ACCESSORIES – Additional options available in our [Accessories Catalog](#) 551444

Position magnets			
			
<p>U-magnet OD33 Part no. 251 416-2</p> <p>Material: PA ferrite GF20 Weight: Approx. 11 g Surface pressure: Max. 40 N/mm² Fastening torque for M4 screws: 1 Nm Operating temperature: -40...+105 °C (-40...+221 °F)</p> <p>Marked version for sensors with internal linearization: Part no. 254 226</p>	<p>Ring magnet OD33 Part no. 201 542-2</p> <p>Material: PA ferrite GF20 Weight: Approx. 14 g Surface pressure: Max. 40 N/mm² Fastening torque for M4 screws: 1 Nm Operating temperature: -40...+105 °C (-40...+221 °F)</p> <p>Marked version for sensors with internal linearization: Part no. 253 620</p>	<p>Ring magnet OD25.4 Part no. 400 533</p> <p>Material: PA ferrite Weight: Approx. 10 g Surface pressure: Max. 40 N/mm² Operating temperature: -40...+105 °C (-40...+221 °F)</p> <p>Marked version for sensors with internal linearization: Part no. 253 621</p>	<p>Ring magnet Part no. 402 316</p> <p>Material: PA ferrite coated Weight: Approx. 13 g Surface pressure: Max. 20 N/mm² Operating temperature: -40...+100 °C (-40...+212 °F)</p>

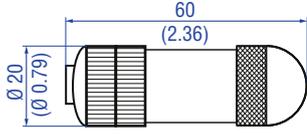
Position magnet	Magnet spacer	O-rings	
			
<p>Block magnet L Part no. 403 448</p> <p>Material: Plastic carrier with hard ferrite magnet Weight: Approx. 20 g Fastening torque for M4 screws: 1 Nm Operating temperature: -40...+75 °C (-40...+167 °F)</p> <p>This magnet may influence the sensor performance specifications for some applications.</p>	<p>Magnet spacer Part no. 400 633</p> <p>Material: Aluminum Weight: Approx. 5 g Surface pressure: Max. 20 N/mm² Fastening torque for M4 screws: 1 Nm</p>	<p>O-ring for threaded flange M18×1.5-6g Part no. 401 133</p> <p>Material: Fluoroelastomer Durometer: 75 ± 5 Shore A Operating temperature: -40...+204 °C (-40...+400 °F)</p>	<p>O-ring for threaded flange ¾"-16 UNF-3A Part no. 560 315</p> <p>Material: Fluoroelastomer Durometer: 75 ± 5 Shore A Operating temperature: -40...+204 °C (-40...+400 °F)</p>

Mounting accessories		
		
<p>Hex jam nut M18×1.5-6g Part no. 500 018</p> <p>Material: Steel, zinc plated</p>	<p>Hex jam nut ¾"-16 UNF-3A Part no. 500 015</p> <p>Material: Steel, zinc plated</p>	<p>Fixing clip Part no. 561 481</p> <p>Application: Used to secure sensor rods (Ø 10 mm (Ø 0.39 in.)) when using an U-magnet or block magnet Material: Brass, non-magnetic</p>

Temposonics® R-Series V RM5 SSI

Data Sheet

Cable connector* Cables

			
<p>M12 A-coded female connector (8 pin), straight Part no. 370 694</p>	<p>PVC cable Part no. 530 032</p>	<p>PUR cable Part no. 530 052</p>	<p>FEP cable Part no. 530 112</p>
<p>Housing: GD-ZnAL Termination: Screw Contact insert: CuZn Cable Ø: 4...9 mm (0.16...0.35 in.) Wire: 0.75 mm² Operating temperature: -25...+90 °C (-13...+194 °F) Ingress protection: IP67 (correctly fitted) Fastening torque: 0.6 Nm</p>	<p>Material: PVC jacket; gray Features: Twisted pair, shielded, flexible Cable Ø: 6 mm (0.23 in.) Cross section: 3 × 2 × 0.14 mm² Bending radius: 10 × D (fixed installation) Operating temperature: -40...+105 °C (-40...+221 °F)</p>	<p>Material: PUR jacket; orange Features: Twisted pair, shielded, highly flexible, halogen free, suitable for drag chains, mostly oil & flame resistant Cable Ø: 6.4 mm (0.25 in.) Cross section: 3 × 2 × 0.25 mm² Bending radius: 5 × D (fixed installation) Operating temperature: -30...+80 °C (-22...+176 °F)</p>	<p>Material: FEP jacket; black Features: Twisted pair, shielded, flexible, high thermal resistance, mostly oil & acid resistant Cable Ø: 7.6 mm (0.3 in.) Cross section: 4 × 2 × 0.25 mm² Bending radius: 8 – 10 × D (fixed installation) Operating temperature: -100...+180 °C (-148...+356 °F)</p>

Cables Cable sets Programming tools

			
<p>PUR cable Part no. 530 175</p>	<p>Cable with M12 A-coded female connector (8 pin), straight – pigtail Part no. 370 674</p>	<p>TempoLink® kit for Temposonics® R-Series V Part no. TL-1-0-SD70 (for D70) Part no. TL-1-0-SD84 (for D84) Part no. TL-1-0-AS00 (for cable outlet)</p>	<p>TempoGate® smart assistant for Temposonics® R-Series V Part no. TG-C-0-Dxx (xx indicates the number of R-Series V sensors that can be connected (even numbers only))</p>
<p>Material: PUR jacket; orange Features: Flexible, additional EMC protection Cable Ø: 6.5 mm (0.26 in.) Cross section: 6 × 0.14 mm² Bending radius: 10 × D (fixed installation) Operating temperature: -30...+90 °C (-22...+194 °F)</p>	<p>Material: PUR jacket; black Features: Shielded Cable length: 5 m (16.4 ft) Ingress protection: IP67/IP69K (correctly fitted) Operating temperature: -25...+80 °C (-13...+176 °F)</p>	<ul style="list-style-type: none"> • Connect wirelessly via Wi-Fi enabled device or via USB with the diagnostic tool • Simple connectivity to the sensor via 24 VDC power line (permissible cable length: 30 m) • User friendly interface for mobile devices and desktop computers • See data sheet "TempoLink® smart assistant" (document part no.: 552070) for further information 	<ul style="list-style-type: none"> • OPC UA server for diagnostics of the R-Series V • For installation in the control cabinet • Connection via LAN and Wi-Fi • See data sheet "TempoGate® smart assistant" document part no.: 552110 for further information

* / Follow the manufacturer's mounting instructions

Controlling design dimensions are in millimeters and measurements in () are in inches

Color of connectors and cable jacket may change. Colors of the cores and technical properties remain unchanged.

ORDER CODE

1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17	18	19	20	21	22	23	24	25	26	27	
R	M	5		A											1	S											
a			b	c	d					e		f			g	h	i	j	k	l	m	n	o				

optional

a	Sensor model
R M 5	Super shield housing

b	Design
M	Threaded flange M18×1.5-6g (standard)
S	Threaded flange ¾"-16 UNF-3A (standard)

c	Mechanical options
A	Standard

d	Stroke length
X X X X M	0025...7615 mm

Standard stroke length (mm)	Ordering steps
25... 500 mm	5 mm
500... 750 mm	10 mm
750...1000 mm	25 mm
1000...2500 mm	50 mm
2500...5000 mm	100 mm
5000...7615 mm	250 mm

X X X X U	001.0...299.8 in.
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Standard stroke length (in.)	Ordering steps
1... 20 in.	0.2 in.
20... 30 in.	0.4 in.
30... 40 in.	1.0 in.
40...100 in.	2.0 in.
100...200 in.	4.0 in.
200...299.8 in.	10.0 in.

Non-standard stroke lengths are available; must be encoded in 5 mm/0.1 in. increments.

e	Number of magnets
X X	01...02 position(s) (1...2 magnet(s))

f	Connection type
H X X	XX m/ft. PUR cable (part no. 530 052) H01...H30 (1...30 m/3...99 ft.) (Note the temperature range of the cable!) See "Frequently ordered accessories" for cable specifications

(Note the temperature range of the cable!)
See "Frequently ordered accessories" for cable specifications

P X X	XX m/ft. PUR cable (part no. 530 175) P01...P30 (1...30 m/3...99 ft.) (Note the temperature range of the cable!) See "Frequently ordered accessories" for cable specifications
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R X X	XX m/ft. PVC cable (part no. 530 032) R01...R30 (1...30 m/3...99 ft.) See "Frequently ordered accessories" for cable specifications
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T X X	XX m/ft. PTFE cable (part no. 530 112) T01...T30 (1...30 m/3...99 ft.) See "Frequently ordered accessories" for cable specifications
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Encode in meters if using metric stroke length.
Encode in feet if using US customary stroke length.

g	System
1	Standard

h	Output
S	SSI

i	Function
---	----------

1	Position
---	----------

2	Differential measurement (2 magnets and 1 output)
---	---

3	Velocity
---	----------

4	Position and temperature in the sensor electronics housing;
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NOTICE In this case, only option **2** "24 bit" can be selected under **1** "Data length".

j	Options
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0	Standard
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1	Internal linearization
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Temposonics® R-Series V RM5 SSI

Data Sheet

k	Mode
1	Measuring direction forward, asynchronous mode
2	Measuring direction forward, synchronous mode 1
3	Measuring direction forward, synchronous mode 2
4	Measuring direction forward, synchronous mode 3
5	Measuring direction reverse, asynchronous mode
6	Measuring direction reverse, synchronous mode 1
7	Measuring direction reverse, synchronous mode 2
8	Measuring direction reverse, synchronous mode 3

l	Data length*
1	25 bit
2	24 bit
3	26 bit
A	24 bit + alarm bit + parity bit

m	Format
B	Binary
G	Gray

n	Resolution
1	5 µm
2	10 µm
3	50 µm
4	100 µm
5	20 µm
6	2 µm
7	0.1 µm*
8	1 µm
9	0.5 µm

o	Additional options (optional)
S 0 0 2	FIR filter (2 measurements)
S 0 0 4	FIR filter (4 measurements)
S 0 0 8	FIR filter (8 measurements)
S 0 0 A	No filter, error counter (4 cycles)
S 0 0 C	No filter, error counter (8 cycles)
S 0 0 D	No filter, error counter (10 cycles)
S 0 0 G	FIR filter (8 measurements), error counter (10 cycles)
S 0 0 J	IIR filter (filter grade 4)
S 0 0 K	IIR filter (filter grade 8)
S 0 0 N	IIR filter (filter grade 8), error counter (10 cycles)

NOTICE

- Specify the number of magnets for your application and order the magnets separately.
- The number of magnets is limited by the stroke length.
The minimum allowed distance between magnets (i.e. front face of one to the front face of the next one) is 75 mm (3 in.).
- Use magnets of the same type for differential measurement.
- If the option for internal linearization in **j** "Options" is chosen, select a suitable magnet.

DELIVERY



- Sensor
- O-ring

Accessories have to be ordered separately.

Manuals, Software & 3D Models available at:
www.temposonics.com

* / The stroke length of the sensor influences the choice of resolution and data width.
See glossary under "Resolution and data width depending on stroke length"

GLOSSARY

A	P
<p>Alarm The alarm bit is set by the sensor if the sensor detects more magnets (extra magnet) or less magnets (magnet status error) than configured.</p> <p>Asynchronous mode In asynchronous mode the position data is continuously updated inside the sensor as quickly as the sensor's measurement cycle will allow, independent of the controller. The controller's loop time will determine when the sensor's most recent data is clocked out over the SSI interface. (→ Synchronous mode)</p>	<p>Parity The parity bit is a check bit that is added to a bit string to detect transmission errors. There are even parity and odd parity. With even parity, the parity bit is set so that the total number of 1-bits in the bit string including the parity bit is even. In case of odd parity, the total number of 1-bits in the bit sequence including the parity bit is odd. Even parity is implemented in the R-Series V SSI.</p>
D	R
<p>Differential measurement For differential measurement, the distance between the two position magnets is output as a value.</p>	<p>Resolution and data width depending on stroke length The stroke length of the sensor influences the choice of resolution and data width. The resolution (step size) and data width (number of steps) must be selected so that the stroke length is covered. For example, with a data width of 24 bit and a resolution of 0.5 µm for an RH5 sensor the maximum stroke length of 7620 mm can be represented. You can adjust the resolution and the data width of the R-Series V SSI via the TempoLink® and TempoGate® smart assistants.</p>
E	S
<p>Extrapolation The native measurement cycle time of a sensor increases with the stroke length. With extrapolation, the sensor is able to report data faster than the native cycle time, independent of the stroke length of the sensor. Without extrapolation, if data is requested faster than the native cycle time, the last measured value is repeated.</p>	<p>Synchronous Serial Interface SSI (Synchronous Serial Interface) is a digital interface where the data is transferred serially. The interface of R-Series V SSI corresponds to SSI industry standard for absolute encoders. Its displacement value is encoded in a 24/25/26 bit binary or gray format and transmitted as a differential signal in SSI standard (RS-485/RS-422).</p>
F	Synchronous mode
<p>FIR filter The FIR filter (Finite Impulse Response) is used to smooth the measured position value before output. To determine the output value, only input values corresponding to the window (filter window size) are used for filter calculation. The output value is calculated from these input values in the form of a moving average value. (→ IIR Filter)</p>	<p>In synchronous mode the measurement and output of the sensor is matched to the data request cycle of the controller. The synchronous mode minimizes the time delay between measurement and output. The synchronous mode is required for sophisticated motion control applications. (→ Asynchronous mode)</p>
I	• Synchronous mode 1
<p>IIR filter The IIR filter (Infinite Impulse Response) is used to smooth the measured position value before output. To determine the output value, the input values corresponding to the filter grade (filter window size) are used for the filter calculation. The previous values are also taken into account when calculating the output value. (→ FIR Filter)</p>	<p>Using synchronous mode 1, the sensor determines the controller's loop timing and when data is being requested. The sensor then determines when to start the next measurement cycle so that it will complete just in time to deliver the freshest data possible.</p>
M	• Synchronous mode 2
<p>Internal linearization The internal linearization offers an improved linearity for an overall higher accuracy of the position measurement. The internal linearization is set for the sensor during production.</p>	<p>If new position data is required faster than the sensor's measurement cycle time, synchronous mode 2 provides extrapolated data values, calculated on the fly. A measurement value will be calculated and output to the controller whenever the sensor has not yet completed the next measurement cycle.</p>
M	• Synchronous mode 3
<p>Measuring direction When moving the position magnet, the position and velocity values increase in the measuring direction.</p> <ul style="list-style-type: none"> • Forward: Values increasing from sensor electronics housing to rod end/profile end • Reverse: Values decreasing from sensor electronics housing to rod end/profile end 	<p>Synchronous mode 3 provides an additional enhancement to the high speed update feature of synchronous mode 2. For this mode all measurements values which are output are calculated to fully compensate for the inherent lag time due to the sensor's measurement cycle.</p>
M	T
M	<p>Temperature in the sensor electronics housing The temperature in the sensor electronics housing is measured in °C. With this option, the transmitted data word has a length of 32 bits, with the highest 8 bits representing the temperature value, followed by 24 bits for the position value. The temperature value is coded in the same format as the position value.</p>

UNITED STATES
Temposonics, LLC
Americas & APAC Region
3001 Sheldon Drive
Cary, N.C. 27513
Phone: +1 919 677-0100
E-mail: info.us@temposonics.com

GERMANY
Temposonics
GmbH & Co. KG
EMEA Region & India
Auf dem Schüffel 9
58513 Lüdenscheid
Phone: +49 2351 9587-0
E-mail: info.de@temposonics.com

ITALY
Branch Office
Phone: +39 030 988 3819
E-mail: info.it@temposonics.com

FRANCE
Branch Office
Phone: +33 6 14 060 728
E-mail: info.fr@temposonics.com

UK
Branch Office
Phone: +44 79 21 83 05 86
E-mail: info.uk@temposonics.com

SCANDINAVIA
Branch Office
Phone: +46 70 29 91 281
E-mail: info.sca@temposonics.com

CHINA
Branch Office
Phone: +86 21 3405 7850
E-mail: info.cn@temposonics.com

JAPAN
Branch Office
Phone: +81 3 6416 1063
E-mail: info.jp@temposonics.com

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