

# $\textbf{Temposonics}^{\circledR}$

Magnetostrictive Linear Position Sensors

# R-Series V RP5 POWERLINK

**Data Sheet** 

- Minimum position resolution  $0.5~\mu m$
- Position and velocity measurements for up to 30 magnets
- Field adjustments and diagnostics using the new TempoLink smart assistant



# **MEASURING TECHNOLOGY**

The absolute, linear position sensors provided by MTS Sensors rely on the company's proprietary Temposonics® magnetostrictive technology, which can determine positions with a high level of precision and robustness.

Each Temposonics® position sensor consists of a ferromagnetic waveguide, a position magnet, a strain pulse converter and supporting electronics. The magnet, connected to the object in motion in the application, generates a magnetic field at its location on the waveguide. A short current pulse is applied to the waveguide. This creates a momentary radial magnetic field and torsional strain on the waveguide. The momentary interaction of the magnetic fields releases a torsional strain pulse that propagates the length of the waveguide. When the ultrasonic wave reaches the end of the waveguide it is converted into an electrical signal. Since the speed of the ultrasonic wave in the waveguide is precisely known, the time required to receive the return signal can be converted into a linear position measurement with both high accuracy and repeatability.

# Position magnet (Magnetic field) Sensing element (Waveguide) Torsional strain pulse converter Measurement Cycle 1 Current pulse generates magnetic field 2 Interaction with position magnet field generates torsional strain pulse 3 Torsional strain pulse propagates 4 Strain pulse detected by converter 5 Time-of-flight converted into position

Fig. 1: Time-of-flight based magnetostrictive position sensing principle

# R-SERIES V POWERLINK

Temposonics® R-Series V brings very powerful sensor performance to meet the many demands of your application. The R-Series V is the long term solution for harsh environments that have high levels of shock and vibration. The sensor is equipped with POWERLINK V2 and supports a minimum cycle time of 250  $\mu s$ . In time-critical applications, the linear extrapolation can be activated. This offers a cycle time of 200  $\mu s$  for every sensor stroke length. The measurement of the sensor can be synchronized to the polling cycle of the controller. Temposonics® R-Series V sensors are available with internal linearization which offers improved linearity for overall higher accuracy of the position measurement values. In addition to the measured position value via the POWERLINK protocol further data about the current sensor status, such like the total distance travelled, the internal temperature and the total operating hours, can be displayed for diagnostic purposes.

With many outstanding features the R-Series V sensors are fit for a very broad range of applications.

# **TempoLink SMART ASSISTANT**

The TempoLink smart assistant is an accessory for the R-Series V family of sensors that supports setup and diagnostics. Depending on the sensor protocol it enables the adjustment of parameters like measurement direction, resolution and filter settings. For diagnostics and analysis of operational data the R-Series V sensors continuously track values such as total distance traveled by the position magnet, internal temperature of the sensor and the quality of the position signal. This additional information can be read out via TempoLink smart assistant even while the sensor remains operational in the application. TempoLink smart assistant is connected to the sensor via the power connection, which now adds bidirectional communication for setup and diagnostics. The TempoLink smart assistant is operated using a graphical user-interface that will be displayed on your smartphone, tablet, laptop or PC. Just connect your Wi-Fi-enabled device to TempoLink Wi-Fi access point and go to the website URL for the user-interface.



Fig. 2: R-Series V sensor with TempoLink smart assistant

# **TECHNICAL DATA**

Output								
Interface	Ethernet POWERLINK							
Data protocol	POWERLINK V2							
Measured value	Position, velocity/option	a. Cimultanaqua	multi pocition and	l multi valacity m	agguramente ur	o to 20 magnata		
	Position, velocity/option	i. Simultaneous	muiti-position and	i illulti-velocity il	ieasurements u	o to 50 magnets		
Measurement parameters	0.5 100 um (calactab	lo)						
Resolution: Position	0.5100 μm (selectable)							
Cycle time	Stroke length Cycle time	≤ 50 mm 250 µs ¹	≤ 715 mm 500 μs	≤ 2000 mm 1000 µs	≤ 4675 mm 2000 μs	≤ 6350 mm 2800 μs		
Linearity deviation <sup>2</sup>	Stroke length	≤ 500 mm	> 500 mm	1000 μ3	2000 μ3	2000 μ3		
	Linearity deviation $\leq \pm 50 \mu\text{m}$ $< 0.01 \%$ F.S.							
	Optional internal linearity: Linearity tolerance (applies for the first magnet for multi-position measurement)							
	Stroke length   25300 mm   300600 mm   6001200 mm   12003000 mm   30005000 mm   50006350 mm							
	typical ± 15 μm		± 25 μm	± 45 μm	± 85 μm	± 95 μm		
	maximum ± 25 μm		± 50 μm	± 90 μm	± 150 µm	± 190 μm		
Repeatability	< ±0.001 % F.S. (minim	ium ±2.5 μm) typ	pical					
Hysteresis		< 4 μm typical						
Temperature coefficient	< 15 ppm/K typical							
Operating conditions								
Operating temperature	-40+85 °C (-40+185 °F)							
Humidity	90 % relative humidity,	no condensation	l					
Ingress protection	IP67 (connectors correctly fitted)							
Shock test	150 g/11 ms, IEC stand	150 g/11 ms, IEC standard 60068-2-27						
Vibration test	30 g/102000 Hz, IEC	standard 60068-	-2-6 (excluding re	sonant frequenci	es)			
EMC test	Electromagnetic emission according to EN 61000-6-3							
	Electromagnetic immunity according to EN 61000-6-2  The sensor meets the requirements of the EC directives and is marked with CE							
		•			ı C E			
Magnet movement velocity	Magnet slider: Max. 10	m/s; U-magnet:	Any; block magne	t: Any				
Design / Material								
Sensor electronics housing	Aluminum (painted), zii	nc die cast						
Sensor profile		Aluminum						
Stroke length	256350 mm (1250	) in.)						
Mechanical mounting								
Mounting position	Any							
Mounting instruction	Please consult the tech	nical drawings o	n page 4					
Electrical connection								
Connection type	2 × M12 female connec	` ' '	M8 male connecto	or (4 pin)				
Operating voltage	+1230 VDC ±20 % (9.636 VDC)							
Power consumption	Less than 4 W typical							
Dielectric strength	500 VDC (DC ground to machine ground)							
Polarity protection	Up to -36 VDC							
Overvoltage protection	Up to 36 VDC							

<sup>1/</sup> Minimum cycle time for multi-position measurements (number of magnets  $\geq$  2): 400  $\mu s$  2/ With position magnet # 252 182

# **TECHNICAL DRAWING**

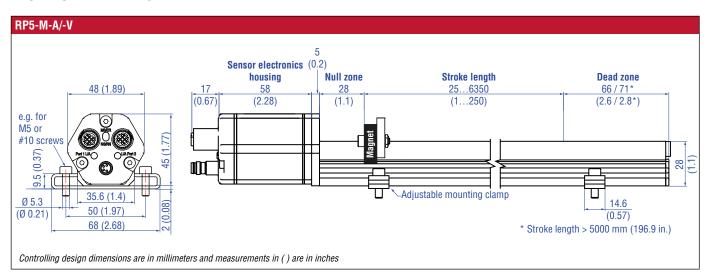


Fig. 3: Temposonics® RP5 with U-magnet

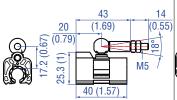
# **CONNECTOR WIRING**

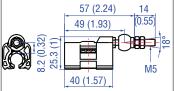
D56			
Signal			
Port 1 – M12 female connector (D-coded)	Pin	Function	
	1	Tx (+)	
3	2	Rx (+)	
(2) (5) (4)	3	Tx (-)	
	4	Rx (-)	
View on sensor	5	Not connected	
Port 2 – M12 female connector (D-coded)	Pin	Function	
	1	Tx (+)	
3	2	Rx (+)	
(2) (5) (4)	3	Tx (-)	
	4	Rx (-)	
View on sensor	5	Not connected	
Power supply			
M8 male connector	Pin	Function	
	1	+1230 VDC (±20 %)	
(0 0)	2	Not connected	
	3	DC Ground (0 V)	
View on sensor	4	Not connected	

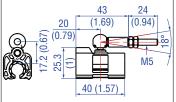
Fig. 4: Connector wiring D56

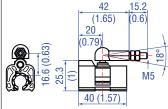
# FREQUENTLY ORDERED ACCESSORIES – Additional options available in our Accessories Guide 551444

# **Position magnets**









## Magnet slider S, joint at top Part no. 252 182

Material: GRP, magnet hard ferrite Weight: Approx. 35 g Operating temperature: -40...+85 °C (-40...+185 °F)

# Magnet slider V, joint at front Part no. 252184

Material: GRP, magnet hard ferrite Weight: Approx. 35 g Operating temperature: -40...+85 °C (-40...+185 °F)

33 (1.3)

19.5 (0.77)

 $8 \pm 2 (0.31 \pm 0.08)$ 

Distance to sensor element

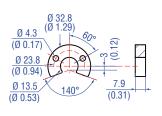
# Magnet slider N longer ball-joint arm Part no. 252 183

Material: GRP, magnet hard ferrite Weight: Approx. 35 g Operating temperature: -40...+85 °C (-40...+185 °F)

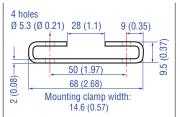
# Magnet slider G, backlash free Part no. 253 421

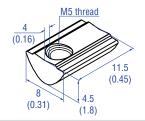
Material: GRP, magnet hard ferrite Weight: Approx. 25 g Operating temperature: -40...+85 °C (-40...+185 °F)

# **Position magnets**



# **Mounting accessories**





## U-magnet 0D33 Part no. 251 416-2

Material: PA ferrite GF20 Weight: Approx. 11 g Surface pressure: Max. 40 N/mm<sup>2</sup> Fastening torque for M4 screws: 1 Nm Operating temperature: -40...+105 °C (-40...+221 °F)

Marked version for sensors with internal linearization: Part no. 254226

# Block magnet L Part no. 403 448

Ø 4.3

 $(\emptyset \ 0.17)$ 

magnet Weight: Approx. 20 g Fastening torque for M4 screws: 1 Nm Operating temperature:

-40...+75 °C (-40...+167 °F)
This magnet may influence the sensor performance specifications for some applications.

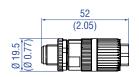
# Mounting clamp Part no. 400 802

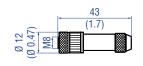
Material: Plastic carrier with hard ferrite Material: Stainless steel (AISI 304)

### 1-nut Part no. 401 602

Fastening torque for M5 screw: 4.5 Nm

# Cable connectors\* Programming kit Cables









# M12 D-coded male connector (4 pin), straight Part no. 370 523

Material: Zinc nickel-plated
Termination: Insulation-displacement
Cable Ø: 5.5...7.2 mm (0.2...0.28 in.)
Wire: 24 AWG – 22 AWG
Operating temperature:
–25...+85 °C (–13...+185 °F)
Ingress protection: IP65 / IP67
(correctly fitted)
Fastening torque: 0.6 Nm

M8 female connector (4 pin), straight Part no. 370 504

Material: CuZn nickel plated
Termination: Solder
Cable Ø: 3.5...5 mm (0.14...0.28 in.)
Wire: 0.25 mm²
Operating temperature:
-40...+85 °C (-40...+185 °F)
Ingress protection: IP67 (correctly fitted)
Fastening torque: 0.5 Nm

# TempoLink kit for Temposonics® R-Series V Part no. TL-1-0-EM08 (for D56)

 Connect wirelessly via Wi-Fi enabled device or via USB with the diagnostic tool

- Simple connectivity to the sensor via 24 VDC power line (permissible cable length: 30 m)
- User friendly interface for mobile devices and desktop computers
- See product brief "TempoLink smart assistant" (document part no.: 551976) for further information

Cable with M8 female connector (4 pin), straight – pigtail

(4 pm), straight – pigran Part no. 530 066 (5 m (16.4 ft.)) Part no. 530 096 (10 m (32.8 ft.)) Part no. 530 093 (15 m (49.2 ft.))

Material: PUR jacket; gray Features: Shielded Cable Ø: 8 mm (0.3 in.) Operating temperature: -40...+90 °C (-40...+194 °F)

## **Cables**









# PUR cable Part no. 530 125

Material: PUR jacket; green Features: Cat 5, highly flexible Cable Ø: 6.5 mm (0.26 in.) Cross section:  $2 \times 2 \times 0.35 \text{ mm}^2$ (22/7 AWG) Operating temperature: -20...+60 °C (-4...+140 °F)

# PVC cable Part no. 530 108

Material: PVC jacket; gray Features: Shielded, flexible Cable Ø: 4.9 mm (0.19 in.) Cross section: 3 × 0.34 mm<sup>2</sup> Operating temperature: -30...+80 °C (-22...+176 °F)

# Cable with M12 D-coded male connector (4 pin), straight – M12 D-coded, male connector (4 pin), straight Part no. 530 064

Material: PUR jacket; green Features: Cat 5e Cable length: 5 m (16.4 ft) Cable Ø: 6.5 mm (0.26 in.) Ingress protection: IP65, IP67, IP68 (correctly fitted) Operating temperature: -30...+70 °C (-22...+158 °F)

# Cable with M12 D-coded male connector (4 pin), straight – RJ45 male connector, straight Part no. 530 065

Material: PUR jacket; green
Features: Cat 5e
Cable length: 5 m (16.4 ft)
Cable Ø: 6.5 mm (0.26 in.)
Ingress protection M12 connector:
IP67 (correctly fitted)
Ingress protection RJ45 connector:
IP20 (correctly fitted)
Operating temperature:
-30...+70 °C (-22...+158 °F)

Controlling design dimensions are in millimeters and measurements in ( ) are in inches

<sup>\*/</sup> Follow the manufacturer's mounting instructions

# ORDER CODE



# a | Sensor model

R P 5 Profile

# b Design

- Magnet slider backlash free (part no. 253 421), suitable for internal linearization
- L Block magnet L (part no. 403 448)
- M U-magnet OD33 (part no. 251 416-2), suitable for internal linearization
- Magnet slider longer ball-jointed arm (part no. 252 183), suitable for internal linearization
- **0** No position magnet
- Magnet slider joint at top (part no. 252 182), suitable for internal linearization
- Magnet slider joint at front (part no. 252 184), suitable for internal linearization

# c Mechanical options

- **A** Standard
- V Fluorelastomer seals for the sensor electronics housing

# d Stroke length

X X X X M 0025...6350 mm

Standard stroke length (mm)	Ordering steps	
25 500 mm	25 mm	
5002500 mm	50 mm	
25005000 mm	100 mm	
50006350 mm	250 mm	

**X** | **X** | **X** | **X** | **U** | 001.0...250.0 in.

Standard stroke length (in.)	Ordering steps	
1 20 in.	1.0 in.	
20100 in.	2.0 in.	
100200 in.	4.0 in.	
200250 in.	10.0 in.	

Non-standard stroke lengths are available; must be encoded in 5 mm / 0.1 in. increments

# e Number of magnets

**X X** 01...30 position(s) (1...30 magnet(s))

# f Connection type

D 5 6 2 × M12 female connectors (5 pin), 1 × M8 male connector (4 pin)

# g System

1 Standard

# h Output

U 3 0 1 POWERLINK, position and velocity (1...30 position(s))

U 3 1 1 POWERLINK, position and velocity, internal linearization (1...30 position(s))

# NOTICE

- For the RP5, the magnet selected in **b** "Design" is included in the scope of delivery. For multi-position measurements with more than 1 magnet, order the other magnets separately.
- The number of magnets is limited by the stroke length.
   The minimum allowed distance between magnets (i.e. front face of one to the front face of the next one) is 75 mm (3 in.).
- Use magnets of the same type for multi-position measurement, e.g. 2 × U-magnet (part no. 251 416-2).
- If the option for internal linearization (U311) in h "Output" is chosen, select a suitable magnet.

Accessories have to be ordered

separately.

# **DELIVERY**



- Sensor
- Position magnet (not valid for RP5 with design »O«)
- 2 mounting clamps up to 1250 mm (50 in.) stroke length
- + 1 mounting clamp for each 500 mm (20 in.) additional stroke length

Manuals, Software & 3D Models available at: www.mtssensors.com



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